

# Waves 2

1. Standing waves
2. Transverse waves in nature: electromagnetic radiation
3. Polarisation
4. Dispersion
5. Information transfer and wave packets
6. Group velocity

# Standing waves

Consider a string with 2 waves of equal amplitude moving in opposite directions

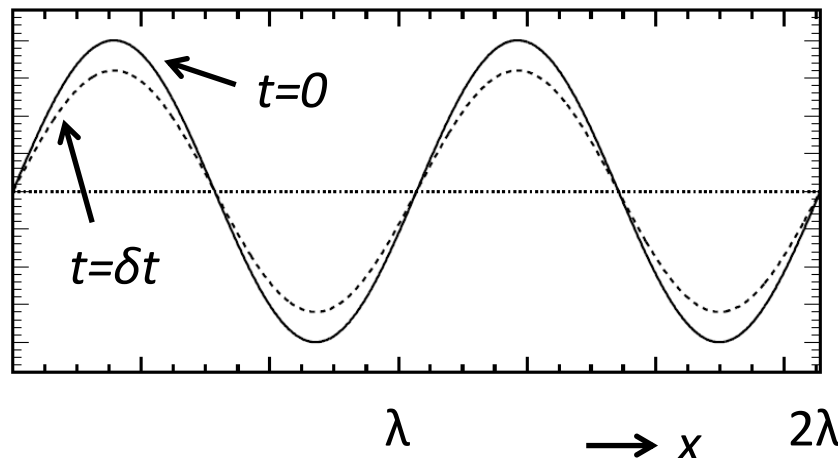
$$\begin{aligned}y(x, t) &= A \sin(kx - \omega t) + A \sin(kx + \omega t) \\ &= 2A \sin kx \cos \omega t\end{aligned}$$

or, if you prefer

$$y(x, t) = 2A \sin\left(\frac{2\pi x}{\lambda}\right) \cos\left(\frac{2\pi t}{T}\right)$$

*i.e.* has factorised into space and time-dependent parts. This means every point on string is moving with a certain time-dependence ( $\cos \omega t$ ), but the amplitude of the motion is a function of the distance from the end of the string

An example –  
a string on two  
which two  
wavelengths  
are excited



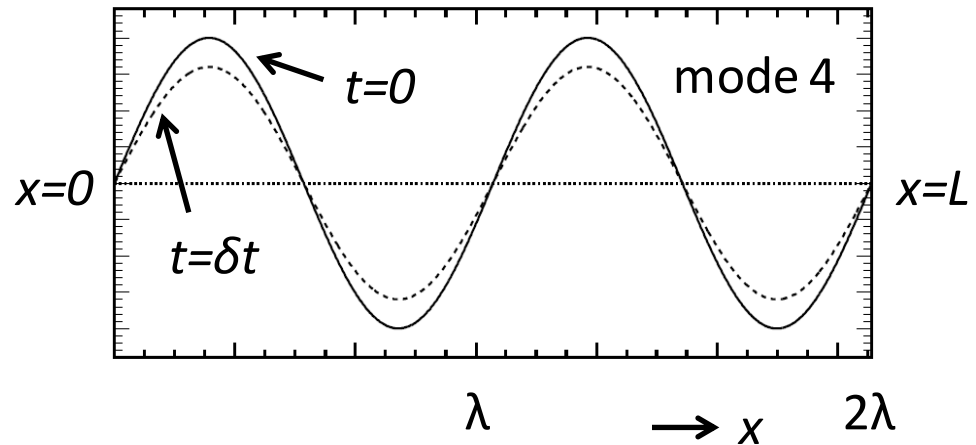
Stationary points  
are the nodes –  
occur every  $\lambda/2$ .  
Between these  
are the antinodes.

# Standing waves

Boundary condition that each end of a fixed string must be a node...

$$y(x,t) = 2A \sin\left(\frac{2\pi x}{\lambda}\right) \cos\left(\frac{2\pi t}{T}\right) \quad \text{with} \quad y(0,t) = y(L,t) = 0$$

...means that only certain discrete frequencies – the modes – are available. These modes are multiples of the basic mode, which is the *fundamental*.



# Standing waves – violin string

E string of a violin is to be tuned to a frequency of 640 Hz. Its length and mass (from bridge to end) are 33 cm and 0.125 g respectively.

What tension is required?



# Transverse waves in nature: EM radiation

The most important example of waves in nature is electromagnetic radiation, *i.e.* light etc. This will be properly covered in EM lectures. Here is just a taster.

Maxwell's equations in free space for electric field **E**, and magnetic inductance **B**

$$\nabla \cdot \mathbf{E} = 0 \quad (1) \quad \nabla \cdot \mathbf{B} = 0 \quad (3)$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad (2) \quad \nabla \times \mathbf{B} = \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \quad (4)$$

$\epsilon_0$  = permittivity of free space =  $8.854 \times 10^{-12}$  F/m

$\mu_0$  = permeability of free space =  $4\pi \times 10^{-7}$  Hm<sup>-1</sup>



James Clerk Maxwell  
1831-1879





# Transverse waves in nature: EM radiation

Maxwell's equations in free space yield:

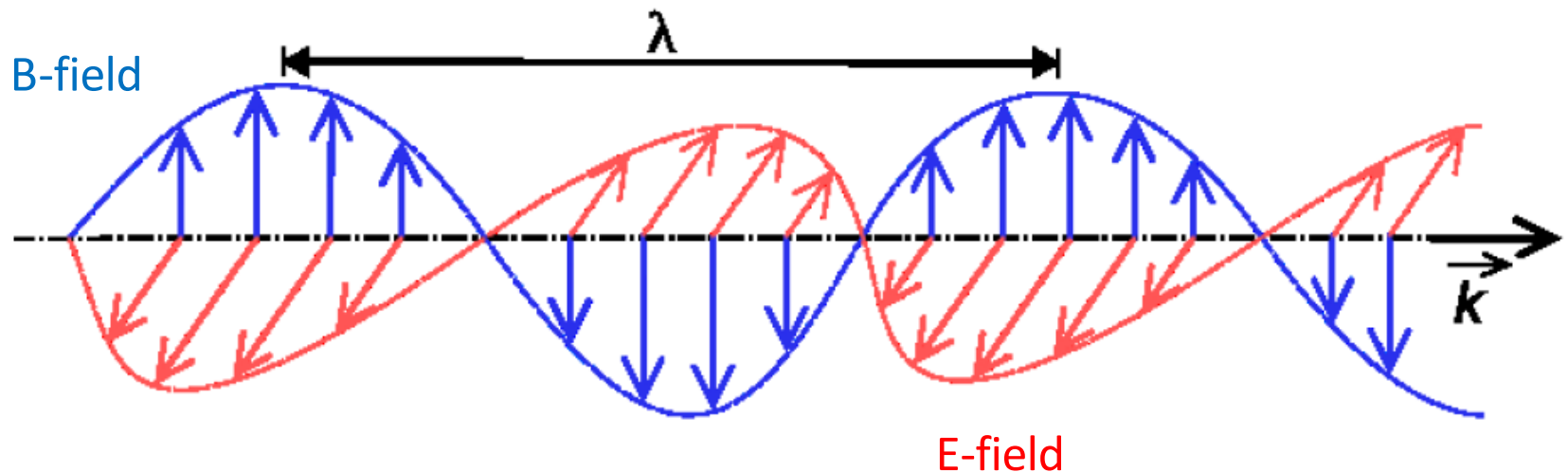
$$\nabla^2 \mathbf{B} = \mu_0 \epsilon_0 \frac{\partial^2 \mathbf{B}}{\partial t^2}$$

(equivalent expression  
is obtainable for  $\mathbf{E}$ )

which is the wave equation with  $c = \frac{1}{\sqrt{\mu_0 \epsilon_0}} = 2.997 \times 10^8 \text{ ms}^{-1} \rightarrow$  the speed of light!

# Transverse waves in nature: EM radiation

EM waves in vacuum: both E and B vectors oscillate transverse to the direction of propagation and, in phase, transverse to each other



# Transverse vs longitudinal waves

For coupled oscillators we considered both transverse and longitudinal excitations. The same is true here – can certainly have longitudinal waves

Some systems support only transverse waves, some only longitudinal, some both

- Transverse only: stretched string, EM waves in vacuum...
- Longitudinal only: sound waves in air – this because air has no elastic resistance to change in shape, only to change in density
- Both: stretched spring, crystal...

Transverse waves have an important attribute not available to longitudinal waves:

POLARISATION



# Polarisation



Transverse vibrations can be in one of two directions (or both) orthogonal to the direction of wave propagation. We talk of two different directions of *polarisation*.

(It can even be that wave velocities are different for the two polarisation states, due to *e.g.* the different interatomic spacings in a crystal.)

Some possibilities for polarisation of E vector in EM wave travelling in z-direction:

# Dispersion

For our stretched string we found that the wave velocity is,  $c = \sqrt{T / \rho}$   
*i.e.* depends only on properties of string and has no dependence on frequency (or wavelength) of wave. But this is an idealised system!

For most systems the velocity of a wave  
*does* have a dependence on  $\omega$  and  $\lambda$

→ DISPERSION

One well known example is light in a prism.  
Light in a medium  $m$  with refractive index  $n$   
Has a velocity  $c_m$ , where  $c_m = c / n$ .

But the refractive index, and hence wave velocity, varies with wavelength. Hence light is bent at different angles by prism according to wavelength.



# Dispersion – lumpy string revisited

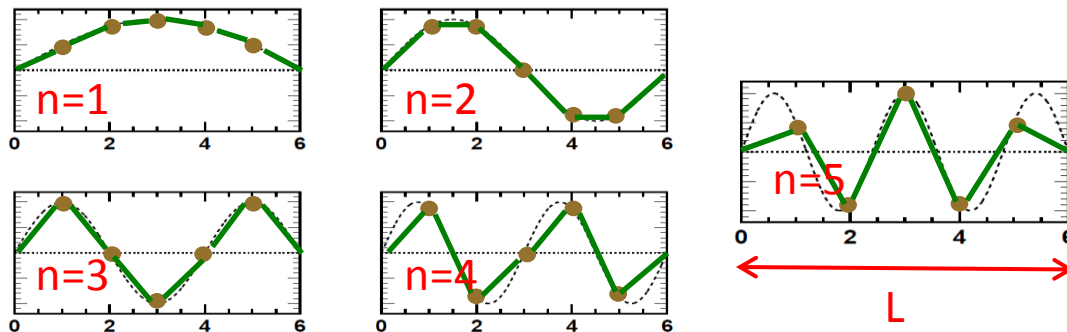
The stretched string has an idealised mass / unit length.

But earlier we analysed normal modes of the lumpy string. We found:

$$\omega_n = 2\omega_0 \sin\left[\frac{n\pi}{2(N+1)}\right] \quad \text{with} \quad \omega_0 = \sqrt{T/mL}$$

and  $\lambda_n = 2L/n$  ; also we have  $k_n \equiv 2\pi/\lambda_n = n\pi/L$

Recall normal modes for  $N=5$ :

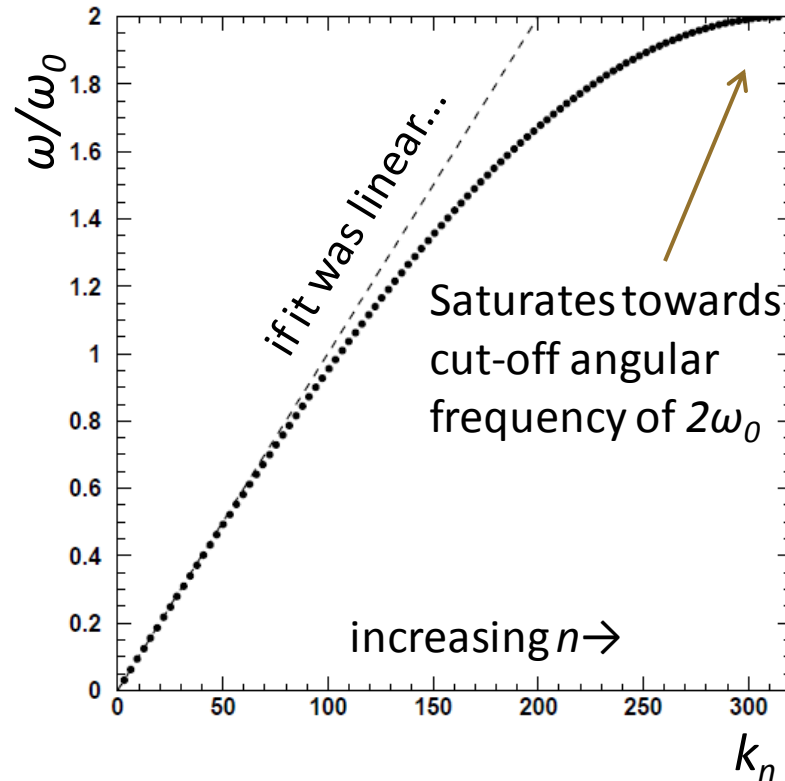


Look at behaviour of  $\omega_n$  vs  $k$  (for  $n=1\dots N$ ), recalling that wave speed= $\omega/k$

# Dispersion curve for lumpy string

For a lumpy string with  $N=100$  masses (other properties arbitrary) calculate  $\omega$  and  $k$  for each normal mode

This is not linear! Velocity of wave corresponding to each mode depends on  $\omega$  (or  $k$ ). This is dispersion.

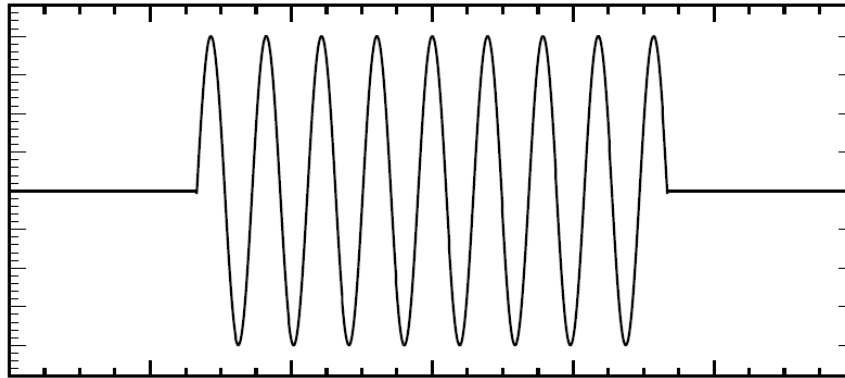


Note also that there is a 'cut-off' frequency – a maximum frequency above which it is not possible to excite system/transmit waves – this is a property often found in a dispersive system.

# Information transfer & wave packets



To transmit information it is necessary to *modulate* a wave.  
Consider the simplest case of turning a wave on and then off:



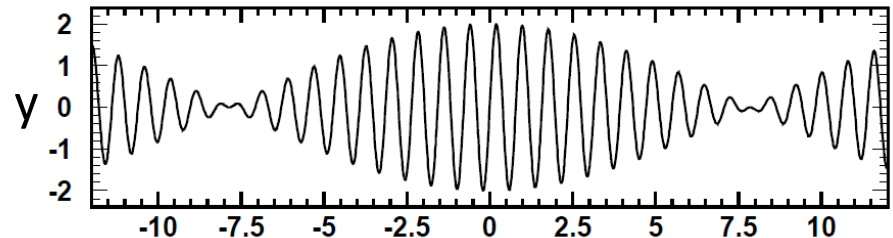
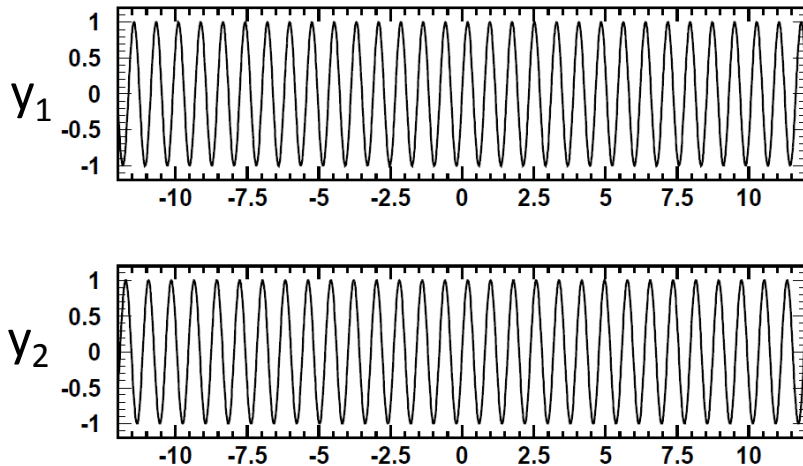
For a certain range of  $(kx - \omega t)$  this signal has displacement  $y = A \sin(kx - \omega t)$ , outside this range the displacement  $y = 0$ . *This is not a single wave*, for which  $y = A \sin(kx - \omega t)$  would apply for *all*  $(kx - \omega t)$ ! It is in fact a wave packet.

# Wave packets – a toy example

Sum together two waves which differ by  $2\delta\omega$  and  $2\delta k$  in angular frequency and wave-number, respectively:

$$y_1 = A \sin[(k + \delta k)x - (\omega + \delta\omega)t]$$
$$y_2 = A \sin[(k - \delta k)x - (\omega - \delta\omega)t]$$

to give  $y = y_1 + y_2 = 2A \cos(\delta k x - \delta\omega t) \sin(kx - \omega t)$



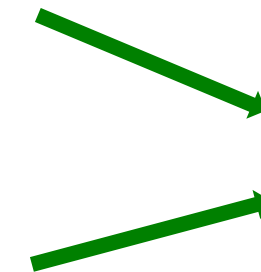
Not exactly a packet, more an infinite series of sausages – would need an infinite number of input waves to make a discrete wave packet

# Modulation

A pure sine wave carries no information – to encode information for radio transmission need to modulate the wave. General principle as follows:

Signal, typically characterised  
by low frequency variation  
(e.g. voice: a few 100 Hz -1kHz)

Carrier wave  
High frequency  
(e.g. ~ MHz)



Modulated signal, which  
is transmitted, received  
and then de-modulated

Carrier signal  
is modulated

Various options exist for the modulation strategy

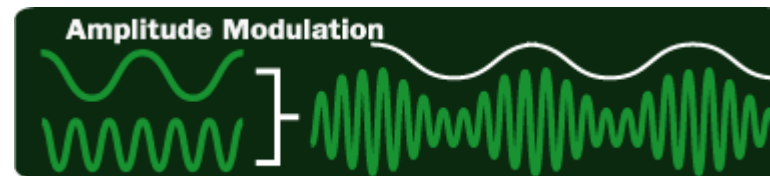
# Modulation strategies

## Pulse modulation



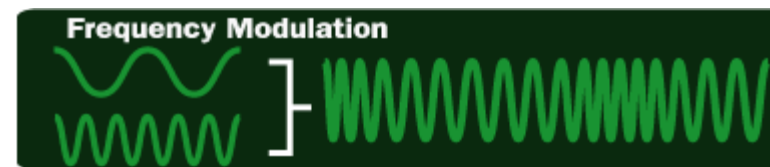
Simply turn sine wave off and on, e.g. morse code

## Amplitude modulation



Modulate amplitude, e.g.  $(\text{Offset} + \text{signal}(t)) \times \sin [2\pi f_{\text{carrier}} t]$

## Frequency modulation



Encode information in modulation of frequency (also phase modulation)

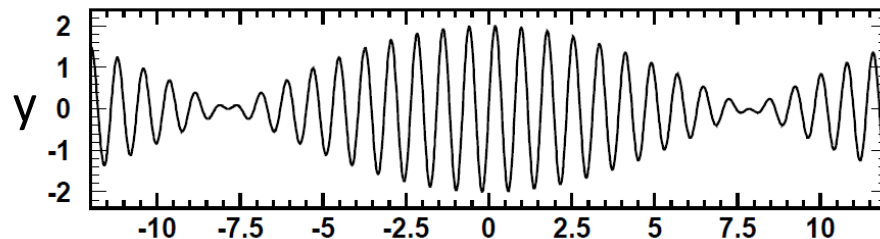


# Group velocity

The velocity of the wave packet is known as the *group velocity*.  
In almost all cases this is the velocity at which information is transmitted.

In a dispersive medium the group velocity is *not* the same as the velocity of the individual waves, which is known as *the phase velocity* (& in a dispersive medium the phase velocity,  $\omega/k$ , varies with frequency & wavelength)

Consider our toy example:



$$y = y_1 + y_2 = 2A \cos(\delta k x - \delta \omega t) \sin(kx - \omega t)$$

Describes envelope – so envelope moves with velocity  $\frac{\delta \omega}{\delta k}$  and indeed

$$\text{Group velocity } v_g = \frac{d\omega}{dk} \quad \text{while phase velocity } v_p = \frac{\omega}{k}$$

# Different expressions for the group velocity

We have already stated

$$v_g = \frac{d\omega}{dk}$$

but  $\omega = v_p k$  so

$$v_g = v_p + k \frac{dv_p}{dk}$$

also, since  $k = 2\pi / \lambda$

$$v_g = v_p - \lambda \frac{dv_p}{d\lambda}$$

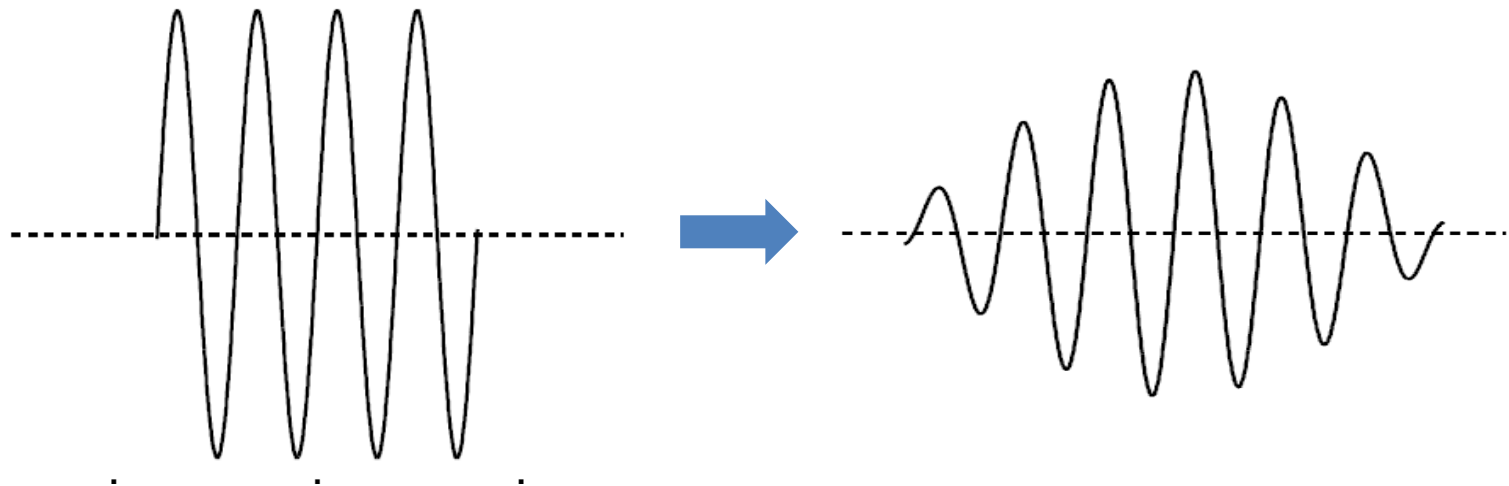
or if considering light, & a medium with refractive index  $n$ , we have  $v_p = c / n$

$$v_g = \frac{c}{n} \left( 1 + \frac{\lambda}{n} \frac{dn}{d\lambda} \right)$$

Observe that  $v_g \neq c / n$ !

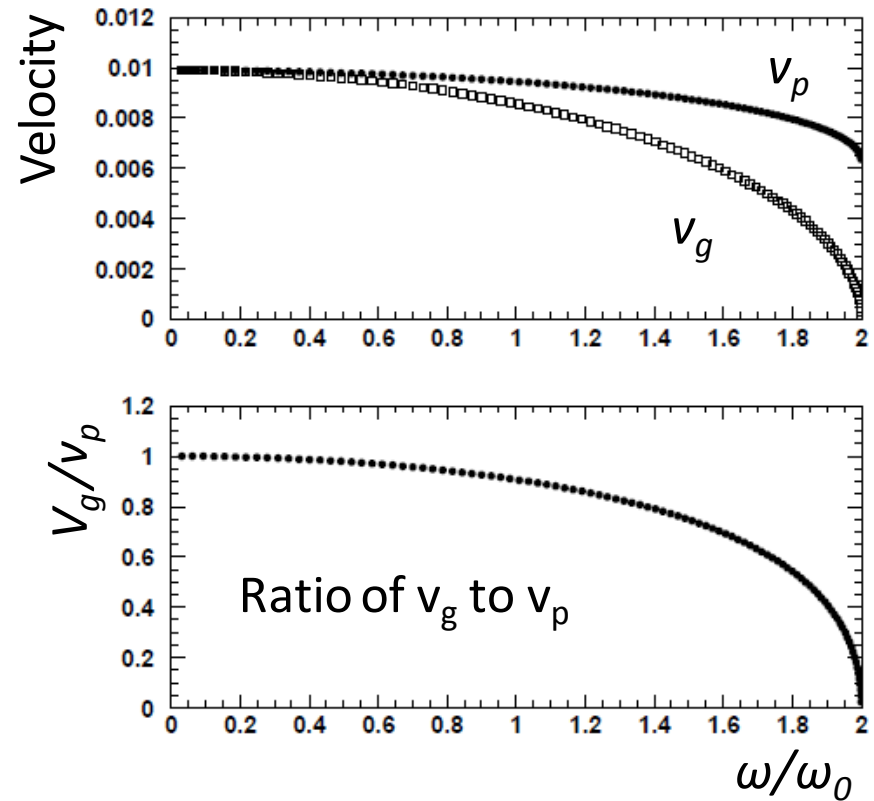
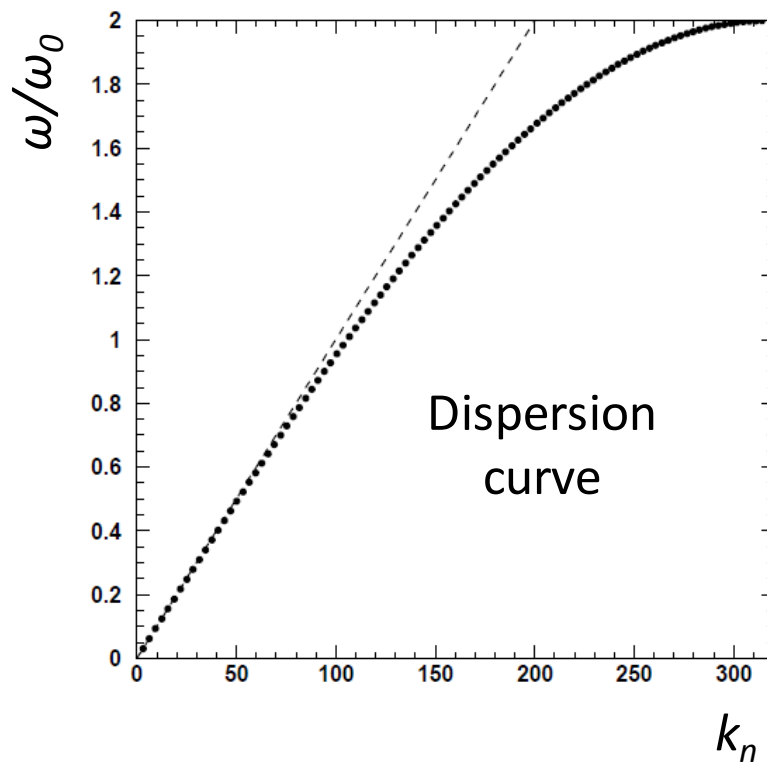
# Dispersion and the spreading of the wave packet

Another consequence of dispersion is that a wave-packet will not retain its shape perfectly, but will spread out. Can have consequences for signal detection



# Group and phase velocities for lumpy string

Calculate phase and group velocity for the lumpy string with  $N=100$



Phase and group velocity  $\sim$  the same at first, but  $v_g \rightarrow 0$  as  $\omega \rightarrow 2\omega_0$  (cut-off)



# Waves in deep water

Waves in water with  $\lambda > 2$  cm (below which surface tension effects are important), but still small compared to water depth, have a dispersion relation