

CP4 revision:

ODE's and complex numbers

Normal Modes, Wave Motion and the Wave Equation

(Worked examples mainly from 2003, 2004 prelims papers)

Week 3: Tuesday, 10am

Week 4: Monday, 10 am, **Thursday, 10am** }

Martin Wood

Optics (Prof J. Jones)

Week 4, Tuesday , 10am, Martin Wood

Functions of complex numbers

● The complex exponential

Functions defined by power series :

$$e^x = 1 + x + \frac{x^2}{2!} + \dots + \frac{x^n}{n!} + \dots$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots + (-1)^n \frac{x^{2n}}{(2n)!} + \dots$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots + (-1)^n \frac{x^{2n+1}}{(2n+1)!} + \dots$$

Define the complex exponential

$$e^\alpha = 1 + \alpha + \frac{\alpha^2}{2!} + \dots + \frac{\alpha^n}{n!} + \dots$$

$$\alpha = a + ib$$

Special case $\alpha = i\theta$

$$e^{i\theta} = \left(1 - \frac{\theta^2}{2!} + \frac{\theta^4}{4!} - \dots\right) + i \left(\theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} - \dots\right)$$

$$= \cos\theta + i \sin\theta$$

The complex logarithm

$\ln z$

$$e^{\ln z} = z = |z| e^{i\theta} = e^{\ln|z|} e^{i\theta} = e^{\ln|z| + i\theta}$$

$$\Rightarrow \ln z = \ln |z| + i \arg(z)$$

Need to know θ including $2\pi n$ phase ambiguity in z

June 2003

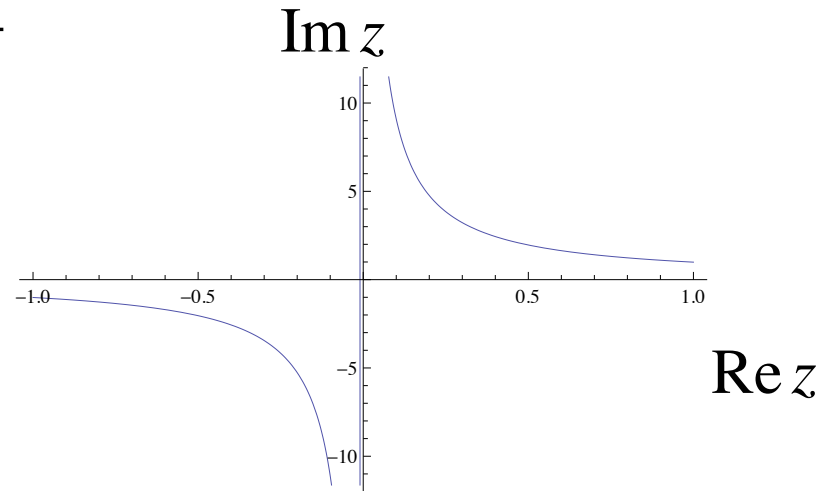
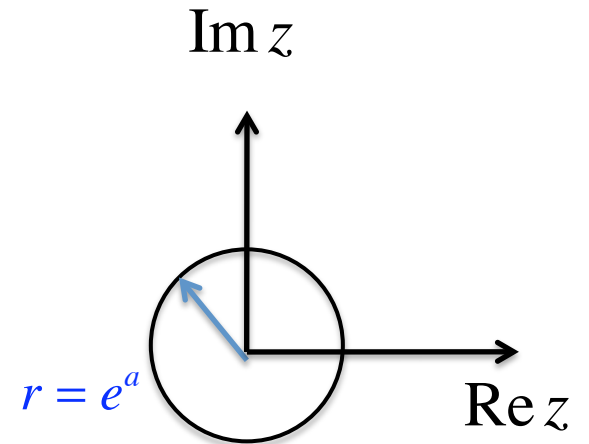
1. Given that a is a real positive constant and z is a complex number, sketch the representations of the following on an Argand diagram. Label your axes clearly.

(a) $\operatorname{Re}\{\ln z\} = a,$

(b) $\operatorname{Im}\{z^2\} = 2a^2.$

(a) $z = re^{i\theta}, \quad \ln r = a, \quad r = e^a$

(b) $z = x + iy, \quad 2xy = 2a^2, \quad y = \frac{a^2}{x}$



June 2004

2. Using complex numbers or otherwise, evaluate the integral $\int_0^y e^{-bx} \sin ax \, dx$.

$$\begin{aligned} \int_0^y e^{-bx} \sin ax \, dx &= \operatorname{Im} \left\{ \int_0^y e^{-bx} e^{iax} \, dx \right\} = \operatorname{Im} \left[\frac{e^{(-b+ia)x}}{-b+ia} \right]_0^y = \operatorname{Im} \frac{e^{-by} (-b-ia)(\cos ax + i \sin ax)}{a^2 + b^2} \\ &= \frac{-e^{-by}}{a^2 + b^2} (a \cos ax + b \sin ax) \end{aligned}$$

September 2003

2. Solve the equation

$$z^6 + z^3 + 1 = 0.$$

$$u = z^3, \quad u^2 + u + 1 = 0, \quad u = \frac{-1 \pm \sqrt{3}i}{2} = e^{i(2\pi/3+n\pi)}, \quad n = 0,1$$

$$z = u^{1/3} = e^{i(2\pi/9+n\pi/3+2m\pi/3)}, \quad n = 0,1, \quad m = 0,1,2$$

2b. Solve the equation $z^6 - 15z^4 + 15z^2 - 1 = 0$

$(x+y)^0$							1
$(x+y)^1$						1	1
$(x+y)^2$				1	2	1	
$(x+y)^3$			1	3	3	1	
$(x+y)^4$		1	4	6	4	1	
$(x+y)^5$	1	5	10	10	5	1	

$$(z+i)^6 = z^6 + 6iz^5 - 15z^4 - 20iz^3 + 15z^2 + 6iz - 1$$

$$(z+i)^6 + (z-i)^6 = 2(z^6 - 15z^4 + 15z^2 - 1) = 0 \Rightarrow \frac{(z+i)^6}{(z-i)^6} \equiv u^6 = -1 = e^{i\pi}$$

$$u = e^{i(\pi/6+2\pi n/6)}, \quad n = 0,1,2,3,4,5$$

$$z-i = u(z+i) \Rightarrow z = \frac{i(1+u)}{(1-u)}$$

First order linear equations

$$\text{General form : } \frac{df}{dx} + q(x)f = h(x).$$

Integrating factor

Look for a function $I(x)$ such that $I(x) \frac{df}{dx} + I(x)q(x)f \equiv \frac{dIf}{dx} = I(x)h(x)$

Easy to solve



$$I(x) = e^{\int q(x') dx'}$$

$$\text{Solution : } f(x) = \frac{1}{I(x)} \int_{x_0}^x I(x')h(x')dx'$$

First order nonlinear equations

Although no general method for solution is available, there are several cases of physically relevant nonlinear equations which can be solved analytically :

Separable equations

$$\frac{dy}{dx} = \frac{f(x)}{g(y)}$$

Solution :

$$\int g(y)dy = \int f(x)dx$$

Almost separable equations

$$\frac{dy}{dx} = f(ax + by)$$

Change variables :

$$z = ax + by$$

$$\frac{dz}{dx} = a + bf(z) \quad \text{Separable}$$

Homogeneous equations

$$\frac{dy}{dx} = f(y/x).$$

Change variables :

$$y = vx$$

$$\frac{dv}{dx} = \frac{1}{x}(f(v) - v) \quad \text{Separable}$$

Homogeneous but for constants

$$\frac{dy}{dx} = \frac{x+2y+1}{x+y+2}$$

Change variables : $x = x' + a$, $y = y' + b$

$$\frac{dy'}{dx'} = \frac{x'+2y'+1+a+2b}{x'+y'+2+a+b} = \frac{x'+2y'}{x'+y'}, \quad a = -3, b = 1 \quad \text{Homogeneous}$$

The Bernoulli equation

$$\frac{dy}{dx} + P(x)y = Q(x)y^n, \quad n \neq 1$$

Change variables : $z = y^{1-n}$

$$\frac{dz}{dx} + (1-n)P(x)z = (1-n)Q(x), \quad \text{First order linear}$$

3. Solve the differential equation

(September 2004)

$$\frac{dy}{dx} - \frac{y}{x} = x,$$

Ist order linear

given that $y = 2$ when $x = 1$.

1. Solve the differential equation

(June 2005)

$$2 \frac{dy}{dx} = \frac{y(x+y)}{x^2}.$$

[6]

Homogeneous

8 (c) $y \frac{dy}{dx} = \frac{x}{4x+3}.$

(June 2007)

Separable

Second order linear equation with constant coefficients

$$Lf = a_2 \frac{d^2 f}{dx^2} + a_1 \frac{df}{dx} + a_0 f = h(x).$$

Complementary function

$$Lf_0 = a_2 \frac{d^2 f_0}{dx^2} + a_1 \frac{df_0}{dx} + a_0 f_0 = 0.$$

Try $f_0 = e^{mx}$



$$a_2 m^2 + a_1 m + a_0 = 0.$$

“Auxiliary” equation

$$m_{\pm} \equiv \frac{-a_1 \pm \sqrt{a_1^2 - 4a_2 a_0}}{2a_2},$$

$a_1^2 - 4a_2 a_0 \rightarrow +, 0, -$



Complementary function

$$f_0 = A_+ e^{m_+ x} + A_- e^{m_- x}.$$

Two constants of integration

Second order linear equation with constant coefficients

$$Lf = a_2 \frac{d^2 f}{dx^2} + a_1 \frac{df}{dx} + a_0 f = h(x).$$

Complementary function

$$Lf_0 = a_2 \frac{d^2 f_0}{dx^2} + a_1 \frac{df_0}{dx} + a_0 f_0 = 0.$$

Try $f_0 = e^{mx}$



$$a_2 m^2 + a_1 m + a_0 = 0.$$

$$m_{\pm} \equiv \frac{-a_1 \pm \sqrt{a_1^2 - 4a_2 a_0}}{2a_2},$$

“Auxiliary” equation

$$a_1^2 - 4a_2 a_0 \rightarrow +, 0, -$$



Complementary function

$$f_0 = Ae^{mx} + Bxe^{mx}$$

Repeated roots

Second order linear equation with constant coefficients

$$Lf = a_2 \frac{d^2 f}{dx^2} + a_1 \frac{df}{dx} + a_0 f = h(x).$$

Complementary function

$$Lf_0 = a_2 \frac{d^2 f_0}{dx^2} + a_1 \frac{df_0}{dx} + a_0 f_0 = 0.$$

Particular integral

$$Lf_1 = a_2 \frac{d^2 f_1}{dx^2} + a_1 \frac{df_1}{dx} + a_0 f_1 = h.$$

General solution : $f_0 + f_1$

June 2003 Q11 Phys

11. A simple pendulum comprises a spherical bob of radius r and density ρ attached to one end of a light rigid rod of length ℓ which hangs vertically under gravity. The bob, which is immersed in a liquid of viscosity η and density ρ_0 , is displaced from its equilibrium position at time $t = 0$ by a small angle α_0 to the vertical and released. The damping force is given by Stokes' formula, $F = 6\pi\eta r v$, where v is the velocity and η the viscosity. Show that the equation of motion of the bob is

$$\ddot{\alpha} + \left(\frac{9\eta}{2r^2\rho} \right) \dot{\alpha} + \left(\frac{\rho - \rho_0}{\rho} \right) \frac{g}{\ell} \alpha = 0.$$

[Archimedes' principle states that a body immersed in a fluid experiences an upthrust equal to the weight of the fluid displaced.]

Solve the equation to obtain an expression for the angular displacement $\alpha(t)$. [9]

Explain what conditions are necessary for the oscillation to be: (a) under damped, and (b) critically damped. Show that for critical damping

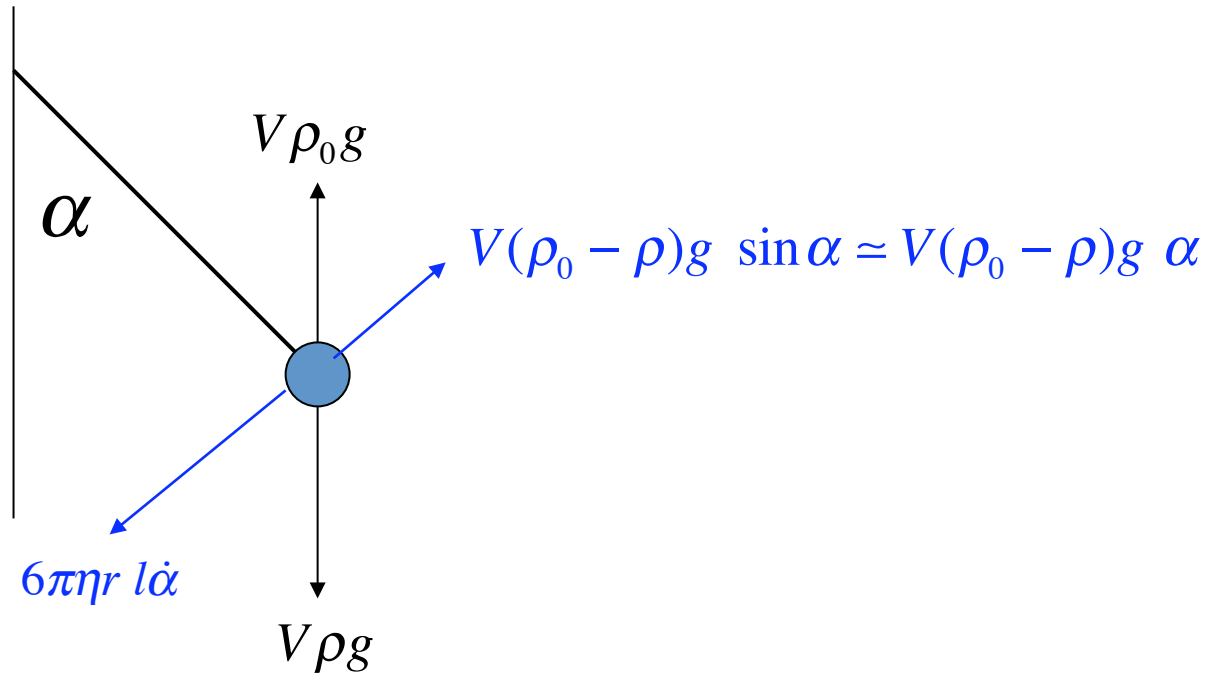
$$r_c = \frac{3}{2} \left[\frac{\eta^2 \ell}{\rho (\rho - \rho_0) g} \right]^{\frac{1}{4}}.$$

For $r > r_c$ (but with all other quantities fixed) state whether the system is over or under damped. [7]

Calculate the radius the bob must have for the motion to be critically damped when $\ell = 0.75$ m and it is immersed in water. [4]

[Take the viscosity of water to be $\eta = 10^{-3} \text{ kg m}^{-1} \text{ s}^{-1}$, the density of the bob to be $\rho = 5 \times 10^3 \text{ kg m}^{-3}$ and the acceleration due to gravity $g = 9.8 \text{ ms}^{-2}$.]

June 2003 Q11 Phys



Newton's 2nd law in direction of motion:

$$V\rho l\ddot{\alpha} = -6\pi\eta r l\dot{\alpha} + V(\rho_0 - \rho)g\alpha$$

$$V = \frac{4}{3}\pi r^3$$

$$\ddot{\alpha} + \frac{6\pi\eta r}{V\rho}\dot{\alpha} + \frac{(\rho_0 - \rho)g}{\rho l}\alpha = 0$$

$$\ddot{\alpha} + \frac{9\eta}{2r^2\rho}\dot{\alpha} + \frac{(\rho_0 - \rho)g}{\rho l}\alpha = 0$$

$$\ddot{\alpha} + A \dot{\alpha} + B \alpha = 0$$

$$\ddot{\alpha} + \frac{9\eta}{2r^2\rho} \dot{\alpha} + \frac{(\rho_0 - \rho)g}{\rho l} \alpha = 0$$

C.F. Try $\alpha = a e^{mt}$

Auxiliary equation : $m^2 + Am + Bm = 0$

$$m_{1,2} = \frac{-A \pm (A^2 - 4B)^{\frac{1}{2}}}{2}$$

$$\alpha(t) = Ae^{m_1 t} + Be^{m_2 t}$$

a). Underdamped: $A^2 < 4B$

b). Critically damped $A^2 = 4B$

$$\left(\frac{9\eta}{2r_c^2\rho} \right)^2 = 4 \frac{g(\rho_0 - \rho)}{l\rho} \Rightarrow r_c = \frac{3}{2} \left(\frac{\eta^2 l}{\rho(\rho - \rho_0)g} \right)^{1/4}$$

$r > r_c$ underdamped