

Final examination

Solutions

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a)  $|j=1, m=-1\rangle = |\downarrow\downarrow\rangle$

$P^{r_{\uparrow\uparrow}} = |\langle \uparrow\uparrow | \Psi \rangle|^2 = \frac{9}{11}$

b)  $\rho = \text{Tr}_A |\Psi\rangle\langle\Psi| = \sum_A \langle \uparrow | \Psi \rangle \langle \Psi | \uparrow \rangle + \sum_A \langle \downarrow | \Psi \rangle \langle \Psi | \downarrow \rangle$   
 $= \frac{1}{11} (|\uparrow\rangle\langle\uparrow| + (i|\uparrow\rangle + 3|\downarrow\rangle)(-i\langle\uparrow| + 3\langle\downarrow|))$

$= \frac{1}{11} \left[ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} 1 & 3i \\ -3i & 9 \end{pmatrix} \right] = \frac{1}{11} \begin{pmatrix} 2 & 3i \\ -3i & 9 \end{pmatrix}$

c)  $\langle S_y \rangle = \text{Tr}(\rho S_y) = \frac{\hbar}{2} \text{Tr}(\rho \sigma_y)$

$= \frac{\hbar}{22} \text{Tr} \left[ \begin{pmatrix} 2 & 3i \\ -3i & 9 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \right] =$

$= \frac{\hbar}{22} \begin{pmatrix} -3 & -3 \end{pmatrix} = -\frac{3\hbar}{11}$

d)  $P^{r_{\sigma_y=1}} = \langle \sigma_y=1 | \rho | \sigma_y=1 \rangle$

$= \frac{1}{22} (1 \ -i) \begin{pmatrix} 2 & 3i \\ -3i & 9 \end{pmatrix} \begin{pmatrix} 1 \\ i \end{pmatrix} = \frac{1}{22} (1 \ -i) \begin{pmatrix} -1 \\ 6i \end{pmatrix} = \frac{5}{22}$

$P^{r_{\sigma_y=-1}} = \langle \sigma_y=-1 | \rho | \sigma_y=-1 \rangle$

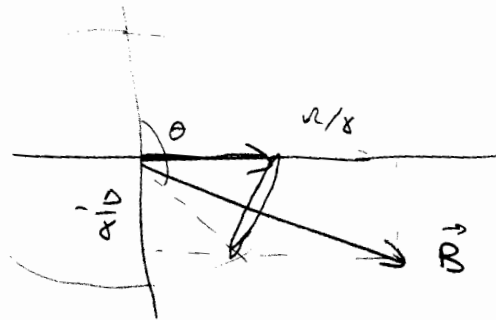
$= \frac{1}{22} (1 \ i) \begin{pmatrix} 2 & 3i \\ -3i & 9 \end{pmatrix} \begin{pmatrix} 1 \\ -i \end{pmatrix} = \frac{1}{22} (1 \ i) \begin{pmatrix} 5 \\ -12i \end{pmatrix} = \frac{17}{22}$

2) a)  $H_{\text{PWA}} = \frac{1}{2} \begin{pmatrix} \Delta - R & \\ -R & -\Delta \end{pmatrix}$  where  $R = \gamma B \tau / 2$ ,  $\Delta = \omega - R_0$

b)  $B_0 = \frac{R_0}{\gamma} = \frac{\omega - \Delta}{\gamma}$

c)  $\theta_B = -\arctan \frac{\Delta}{R}$

d)



e) One-half Larmor period:  $\frac{\pi}{\sqrt{R^2 + \Delta^2}}$

f)  $\theta = \frac{\pi}{2} + 2 \arctan \frac{\Delta}{R}$ ,  $\psi = 0$

g)  $z = 1 - (1 - z_0) e^{-t/\tau}$ , where  $z_0 = -\tan(2 \arctan \frac{\Delta}{R})$

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$$|j\rangle = |e_1 + e_2\rangle, m = e_1 + e_2 \Rightarrow |m_1 = e_1, m_2 = e_2\rangle$$

$$\Rightarrow \langle e_1 + e_2, e_1 + e_2 | e_1, e_2 \rangle = 1$$

$$J_- |e_1 + e_2, e_1 + e_2\rangle = (L_{1-} + L_{2-}) |e_1, e_2\rangle$$

$$\begin{aligned} & \sqrt{(e_1 + e_2)(e_1 + e_2 + 1) - (e_1 + e_2)(e_1 + e_2 - 1)} |e_1 + e_2, e_1 + e_2 - 1\rangle \\ & = \sqrt{e_1(e_1 + 1) - e_1(e_1 - 1)} |e_1 - 1, e_2\rangle + \sqrt{e_2(e_2 + 1) - e_2(e_2 - 1)} |e_1, e_2 - 1\rangle \end{aligned}$$

$$e_2 = \frac{1}{2} \Rightarrow \sqrt{(e_1 + \frac{1}{2})(e_1 + \frac{3}{2}) - (e_1 + \frac{1}{2})(e_1 - \frac{1}{2})} |e_1 + \frac{1}{2}, e_1 - \frac{1}{2}\rangle$$

$$= \sqrt{2e_1} |e_1 - 1, \frac{1}{2}\rangle + |e_1, -\frac{1}{2}\rangle$$

$$\sqrt{2(e_1 + \frac{1}{2})} |e_1 + \frac{1}{2}, e_1 - \frac{1}{2}\rangle = \sqrt{2e_1} |e_1 - 1, \frac{1}{2}\rangle + |e_1, -\frac{1}{2}\rangle \quad (1)$$

$$\langle e_1 + \frac{1}{2}, e_1 - \frac{1}{2} | e_1 - 1, \frac{1}{2} \rangle = \frac{\sqrt{2e_1}}{\sqrt{2e_1 + 1}}$$

$$\langle e_1 + \frac{1}{2}, e_1 - \frac{1}{2} | e_1, -\frac{1}{2} \rangle = \frac{1}{\sqrt{2e_1 + 1}}$$

State orthogonal to (1):

$$|e_1 - \frac{1}{2}, e_1 - \frac{1}{2}\rangle = \pm \frac{1}{\sqrt{2e_1 + 1}} |e_1 - 1, \frac{1}{2}\rangle \mp \frac{\sqrt{2e_1}}{\sqrt{2e_1 + 1}} |e_1, -\frac{1}{2}\rangle$$

$$\langle e_1 - \frac{1}{2}, e_1 - \frac{1}{2} | e_1 - 1, \frac{1}{2} \rangle = \pm \frac{1}{\sqrt{2e_1 + 1}}$$

$$\langle e_1 - \frac{1}{2}, e_1 - \frac{1}{2} | e_1, -\frac{1}{2} \rangle = \mp \frac{\sqrt{2e_1}}{\sqrt{2e_1 + 1}}$$

$$\boxed{4} \quad a) \quad H = \hbar A X, P_2$$

$$\dot{X}_1 = \frac{i}{\hbar} [H, X_1] = 0$$

$$\dot{X}_2 = \frac{i}{\hbar} [H, X_2] = \frac{i}{\hbar} (-i) \hbar A X_1 = A X_1$$

$$\dot{P}_1 = \frac{i}{\hbar} [H, P_1] = \frac{i}{\hbar} (i) \hbar A P_2 = -A P_2$$

$$\dot{P}_2 = \frac{i}{\hbar} [H, P_2] = 0$$

$$b) \quad X_1(t) = X_1(0)$$

$$X_2(t) = X_2(0) + A X_1(0) t$$

$$P_1(t) = P_1(0) - A P_2(0) t$$

$$P_2(t) = P_2(0)$$

$$c) \quad \langle X_{1,2}(t) \rangle = \langle P_{1,2}(t) \rangle = 0$$

$$\begin{aligned} \langle \Delta (X_1 \pm X_2)^2 \rangle &= \langle \Delta [(1 \pm A t) X_1(0) + X_2(0)]^2 \rangle \\ &= \frac{1}{2} [(1 \pm A t)^2 + 1] \quad (= 1 \text{ for } t=0) \end{aligned}$$

$$\begin{aligned} \langle \Delta (P_1 \pm P_2)^2 \rangle &= \langle \Delta [P_1(0) \pm (-A t \pm 1) P_2(0)]^2 \rangle \\ &= \frac{1}{2} [1 + (-A t \pm 1)^2] \quad (= 1 \text{ for } t=0) \end{aligned}$$

Squeezing is present if either  $(1 \pm A t)^2$  or  $(-A t \pm 1)^2$  are less than one, i.e. when  $|A t| < 2$ .

$$d) \quad e^{-i H t / \hbar} |00\rangle$$

$$= (1 - i \frac{H t}{\hbar}) |00\rangle$$

$$= (1 - i A X, P_2 t) |00\rangle$$

$$= |00\rangle - i A t \frac{(a_+ + a_+^\dagger)(a_- - a_-^\dagger)}{2} |00\rangle$$

$$= |00\rangle + \frac{A t}{2} |11\rangle \equiv |\Psi\rangle$$

$$e) \quad \langle \Psi | (X_1 \pm X_2)^2 | \Psi \rangle$$

$$= \left( \langle 00 | + \frac{A t}{2} \langle 11 | \right) \left( \frac{a_1 + a_1^\dagger \pm a_2 \pm a_2^\dagger}{\sqrt{2}} \right)^2 \left( |00\rangle + \frac{A t}{2} |11\rangle \right)$$

$$= \frac{1}{2} \left[ \langle 00 | a_1 a_1^\dagger + a_2 a_2^\dagger | 00 \rangle \pm \frac{A t}{2} \langle 00 | a_1 a_2 | 11 \rangle \pm \frac{A t}{2} \langle 11 | a_1^\dagger a_2^\dagger | 00 \rangle \right]$$

$$= 1 \pm A t$$

Same as  $\frac{1}{2} [(1 \pm A t)^2 + 1]$  for  $A t \ll 1$ .

5) a)  $S_z = \frac{\hbar}{2} (|\uparrow\rangle\langle\uparrow| - |\downarrow\rangle\langle\downarrow|)$

$H = c\hbar S_z \otimes S_z = \frac{c\hbar^3}{4} (|\uparrow\uparrow\rangle\langle\uparrow\uparrow| - |\uparrow\downarrow\rangle\langle\uparrow\downarrow| - |\downarrow\uparrow\rangle\langle\downarrow\uparrow| + |\downarrow\downarrow\rangle\langle\downarrow\downarrow|)$   
 $= \frac{c\hbar^3}{4} \begin{pmatrix} 1 & & & \\ & -1 & & \\ & & -1 & \\ & & & 1 \end{pmatrix}$

b)  $|\psi(0)\rangle = \frac{1}{2} (|\uparrow\rangle + |\downarrow\rangle) \otimes (|\uparrow\rangle + |\downarrow\rangle) = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$

c)  $|\psi(t)\rangle = e^{-iHt/\hbar} |\psi(0)\rangle = \frac{1}{2} \begin{pmatrix} e^{-i\omega t} & & & \\ & e^{i\omega t} & & \\ & & e^{i\omega t} & \\ & & & e^{-i\omega t} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} e^{-i\omega t} \\ e^{i\omega t} \\ e^{i\omega t} \\ e^{-i\omega t} \end{pmatrix}$

where  $\omega = \frac{c\hbar^2}{4}$

d)  $|\psi(t)\rangle = \frac{1}{2} (e^{-i\omega t} |\uparrow\uparrow\rangle + e^{i\omega t} |\uparrow\downarrow\rangle + e^{i\omega t} |\downarrow\uparrow\rangle + e^{-i\omega t} |\downarrow\downarrow\rangle)$

$\langle\uparrow|\psi(t)\rangle = \frac{1}{2} (e^{-i\omega t} |\uparrow\rangle + e^{i\omega t} |\downarrow\rangle) = \frac{1}{2} \begin{pmatrix} e^{-i\omega t} \\ e^{i\omega t} \end{pmatrix}$   $pr = \frac{1}{2}$

$\langle\downarrow|\psi(t)\rangle = \frac{1}{2} (e^{i\omega t} |\uparrow\rangle + e^{-i\omega t} |\downarrow\rangle) = \frac{1}{2} \begin{pmatrix} e^{i\omega t} \\ e^{-i\omega t} \end{pmatrix}$   $pr = \frac{1}{2}$

$\rho = \frac{1}{4} \begin{pmatrix} 1 & e^{-2i\omega t} \\ e^{2i\omega t} & 1 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 1 & e^{2i\omega t} \\ e^{-2i\omega t} & 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 & \cos 2\omega t \\ \cos 2\omega t & 1 \end{pmatrix}$

e)  $\langle + | \psi(t) \rangle = \frac{1}{2\sqrt{2}} (e^{-i\omega t} |\uparrow\rangle + e^{i\omega t} |\downarrow\rangle + e^{i\omega t} |\uparrow\rangle + e^{-i\omega t} |\downarrow\rangle)$

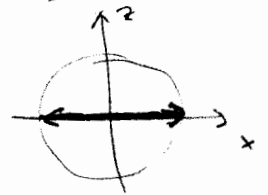
$= \frac{1}{\sqrt{2}} \cos \omega t (|\uparrow\rangle + |\downarrow\rangle) = \cos \omega t |+\rangle$   $pr = \cos^2 \omega t$

$\langle - | \psi(t) \rangle = \frac{1}{2\sqrt{2}} (e^{-i\omega t} |\uparrow\rangle + e^{i\omega t} |\downarrow\rangle - e^{i\omega t} |\uparrow\rangle - e^{-i\omega t} |\downarrow\rangle)$

$= \frac{i}{\sqrt{2}} \sin \omega t (|\downarrow\rangle - |\uparrow\rangle) = -i \sin \omega t |-\rangle$   $pr = \sin^2 \omega t$

$\rho = \cos^2 \omega t |+\rangle\langle +| + \sin^2 \omega t |-\rangle\langle -| = \frac{1}{2} \begin{pmatrix} 1 & \cos 2\omega t \\ \cos 2\omega t & 1 \end{pmatrix}$

d)  $\vec{R} = \frac{1}{2} (\cos^2 \omega t R_{|+\rangle} + \sin^2 \omega t R_{|-\rangle})$



g)  $H' = \mu B = \mu_B B S_z = \mu_B B \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

$e^{-iH'(t-t_1)/\hbar} = \begin{pmatrix} e^{-i\mathcal{Q}(t-t_1)} & 0 \\ 0 & e^{i\mathcal{Q}(t-t_1)} \end{pmatrix}$  where  $\mathcal{Q} = \frac{\mu_B B}{\hbar}$

$\rho(t) = e^{-iH'(t-t_1)/\hbar} \rho(t_1) e^{iH'(t-t_1)/\hbar} = \frac{1}{2} \begin{pmatrix} 1 & \cos 2\omega t e^{-2i\mathcal{Q}(t-t_1)} \\ \cos 2\omega t_1 e^{2i\mathcal{Q}(t-t_1)} & 1 \end{pmatrix}$