

*LECTURE 2:*  
*VECTOR MULTIPLICATION -*  
*SCALAR AND VECTOR*  
*PRODUCTS*

Prof. N. Harnew  
University of Oxford  
MT 2012

## *Outline: 2. VECTOR MULTIPLICATION*

### *2.1 Scalar Product*

2.1.1 Properties of scalar product

2.1.2 Angle between two vectors

### *2.2 Vector Product*

2.2.1 Properties of vector products

2.2.2 Vector product of unit vectors

2.2.3 Vector product in components

2.2.4 Geometrical interpretation of vector product

### *2.3 Examples*

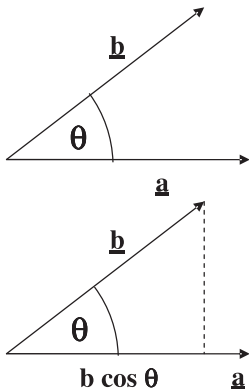
## 2.1 Scalar Product

Scalar (or dot) product definition:

$$\underline{\mathbf{a}} \cdot \underline{\mathbf{b}} = |\underline{\mathbf{a}}| \cdot |\underline{\mathbf{b}}| \cos \theta \equiv ab \cos \theta$$

(write shorthand  $|\underline{\mathbf{a}}| = a$  ).

- ▶ Scalar product is the magnitude of  $\underline{\mathbf{a}}$  multiplied by the projection of  $\underline{\mathbf{b}}$  onto  $\underline{\mathbf{a}}$ .
- ▶ Obviously if  $\underline{\mathbf{a}}$  is perpendicular to  $\underline{\mathbf{b}}$  then  $\underline{\mathbf{a}} \cdot \underline{\mathbf{b}} = 0$
- ▶ Also  $\underline{\mathbf{a}} \cdot \underline{\mathbf{a}} = |a|^2$  (since  $\theta = 0^\circ$ )  
Hence  $a = \sqrt{(\underline{\mathbf{a}} \cdot \underline{\mathbf{a}})}$



## 2.1.1 Properties of scalar product

- (i)  $\underline{\mathbf{i}} \cdot \underline{\mathbf{i}} = \underline{\mathbf{j}} \cdot \underline{\mathbf{j}} = \underline{\mathbf{k}} \cdot \underline{\mathbf{k}} = 1$  and  $\underline{\mathbf{i}} \cdot \underline{\mathbf{j}} = \underline{\mathbf{j}} \cdot \underline{\mathbf{k}} = \underline{\mathbf{k}} \cdot \underline{\mathbf{i}} = 0$
- (ii) This leads to  $\underline{\mathbf{a}} \cdot \underline{\mathbf{b}} = (a_x \underline{\mathbf{i}} + a_y \underline{\mathbf{j}} + a_z \underline{\mathbf{k}}) \cdot (b_x \underline{\mathbf{i}} + b_y \underline{\mathbf{j}} + b_z \underline{\mathbf{k}})$   
 $= a_x b_x + a_y b_y + a_z b_z$  (this is a very useful relation)
- iii)  $\underline{\mathbf{a}} \cdot \underline{\mathbf{b}} = \underline{\mathbf{b}} \cdot \underline{\mathbf{a}}$  : commutative  
 $\underline{\mathbf{a}} \cdot (\underline{\mathbf{b}} + \underline{\mathbf{c}}) = \underline{\mathbf{a}} \cdot \underline{\mathbf{b}} + \underline{\mathbf{a}} \cdot \underline{\mathbf{c}}$  : distributive
- (iv) If  $\underline{\mathbf{c}} = \underline{\mathbf{a}} + \underline{\mathbf{b}}$   
Then  $c^2 = \underline{\mathbf{c}} \cdot \underline{\mathbf{c}} = (\underline{\mathbf{a}} + \underline{\mathbf{b}}) \cdot (\underline{\mathbf{a}} + \underline{\mathbf{b}})$   
 $= a^2 + b^2 + 2\underline{\mathbf{a}} \cdot \underline{\mathbf{b}} = a^2 + b^2 + 2ab \cos(\theta_{ab})$
- (v) Parentheses are important  
Note  $(\underline{\mathbf{u}} \cdot \underline{\mathbf{v}}) \underline{\mathbf{w}} \neq \underline{\mathbf{u}} (\underline{\mathbf{v}} \cdot \underline{\mathbf{w}})$  because one is a vector along  $\underline{\hat{\mathbf{w}}}$ ,  
the other is along  $\underline{\hat{\mathbf{u}}}$ .

## 2.1.2 Angle between two vectors

$$\text{By definition } \cos(\theta) = \frac{\mathbf{a} \cdot \mathbf{b}}{ab}$$

### Example

- ▶ The angle between vectors  $\mathbf{a} = (3, 1, 5)$  and  $\mathbf{b} = (2, 1, 3)$
- ▶  $\cos \theta = \frac{3 \times 2 + 1 \times 1 + 5 \times 3}{\sqrt{(3^2 + 1^2 + 5^2)} \times \sqrt{(2^2 + 1^2 + 3^2)}} = \frac{22}{\sqrt{(35)} \times \sqrt{(14)}} = 0.994$
- ▶  $\theta = 6.3^\circ$

### Example of scalar products in physics

- ▶ Work done on a body by a force through distance  $\mathbf{dx}$
- ▶  $dW = \mathbf{F} \cdot \mathbf{dx}$
- ▶ Only the component of force parallel to displacement does work.

## 2.2 Vector Product

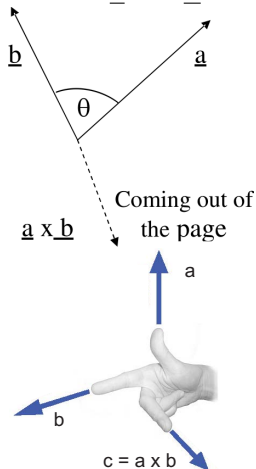
Vector (or cross) product of two vectors, definition:

$$\underline{a} \times \underline{b} = |\underline{a}| |\underline{b}| \sin\theta \hat{n}$$

where  $\hat{n}$  is a *unit vector* in a direction *perpendicular* to both  $\underline{a}$  and  $\underline{b}$ .

To get direction of  $\underline{a} \times \underline{b}$  use right hand rule:

- ▶ i) Make a set of directions with your *right hand* → thumb & first index finger, and with middle finger positioned perpendicular to plane of both
- ▶ ii) Point your thumb along the first vector  $\underline{a}$
- ▶ iii) Point your 1st index finger along  $\underline{b}$ , making the smallest possible angle to  $\underline{a}$
- ▶ iv) The direction of the middle finger gives the direction of  $\underline{a} \times \underline{b}$ .



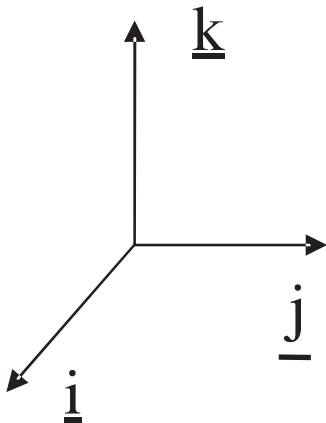
## 2.2.1 Properties of vector product

- ▶  $(\underline{\mathbf{a}} + \underline{\mathbf{b}}) \times \underline{\mathbf{c}} = (\underline{\mathbf{a}} \times \underline{\mathbf{c}}) + (\underline{\mathbf{b}} \times \underline{\mathbf{c}})$  : distributive
- ▶  $\underline{\mathbf{a}} \times \underline{\mathbf{b}} = -\underline{\mathbf{b}} \times \underline{\mathbf{a}}$  : NON-commutative
- ▶  $(\underline{\mathbf{a}} \times \underline{\mathbf{b}}) \times \underline{\mathbf{c}} \neq \underline{\mathbf{a}} \times (\underline{\mathbf{b}} \times \underline{\mathbf{c}})$  : NON-associative
- ▶ If  $m$  is a scalar,  
$$m(\underline{\mathbf{a}} \times \underline{\mathbf{b}}) = (m\underline{\mathbf{a}}) \times \underline{\mathbf{b}} = \underline{\mathbf{a}} \times (m\underline{\mathbf{b}}) = (\underline{\mathbf{a}} \times \underline{\mathbf{b}})m.$$
- ▶ Importantly  $\underline{\mathbf{a}} \times \underline{\mathbf{b}} = \mathbf{0}$  if vectors are parallel ( $0^\circ$ )  
i.e  $\underline{\mathbf{a}} \times \underline{\mathbf{a}} = \mathbf{0}$

## 2.2.2 Vector product of unit vectors

The basis vectors are connected by cyclic permutations of vector products (another good way to remember the right hand rule)

- ▶  $\underline{\mathbf{i}} \times \underline{\mathbf{j}} = \underline{\mathbf{k}}$
- ▶  $\underline{\mathbf{j}} \times \underline{\mathbf{k}} = \underline{\mathbf{i}}$
- ▶  $\underline{\mathbf{k}} \times \underline{\mathbf{i}} = \underline{\mathbf{j}}$





## 2.2.3 Vector product in components

A very useful property:

- ▶  $\underline{\mathbf{a}} \times \underline{\mathbf{b}} = (a_x, a_y, a_z) \times (b_x, b_y, b_z)$   
 $= (a_x \underline{\mathbf{i}} + a_y \underline{\mathbf{j}} + a_z \underline{\mathbf{k}}) \times (b_x \underline{\mathbf{i}} + b_y \underline{\mathbf{j}} + b_z \underline{\mathbf{k}})$
- ▶ Since  $\underline{\mathbf{i}} \times \underline{\mathbf{i}} = \underline{\mathbf{j}} \times \underline{\mathbf{j}} = \underline{\mathbf{k}} \times \underline{\mathbf{k}} = 0$  and  $\underline{\mathbf{i}} \times \underline{\mathbf{j}} = \underline{\mathbf{k}}$  etc.
- ▶  $\underline{\mathbf{a}} \times \underline{\mathbf{b}} = (a_y b_z - a_z b_y) \underline{\mathbf{i}} - (a_x b_z - a_z b_x) \underline{\mathbf{j}} + (a_x b_y - a_y b_x) \underline{\mathbf{k}}$

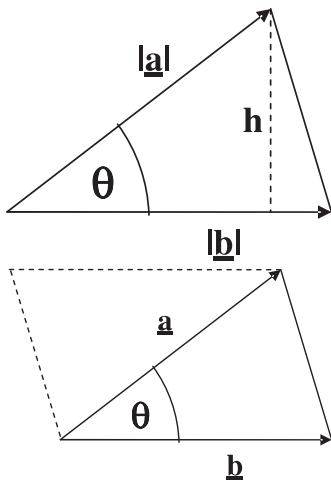
This is much easier when we write in *determinant* form:

$$\underline{\mathbf{a}} \times \underline{\mathbf{b}} = \begin{vmatrix} \underline{\mathbf{i}} & \underline{\mathbf{j}} & \underline{\mathbf{k}} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix}. \quad (1)$$

## 2.2.4 Geometrical interpretation of vector product

Vector product is related to the area of a triangle:

- ▶ Height of triangle  $h = a \sin\theta$
- ▶ Area of triangle =  $A_{\text{triangle}} = \frac{1}{2} \times \text{base} \times \text{height}$   
 $= \frac{bh}{2} = \frac{ab \sin\theta}{2} = \frac{|\underline{\mathbf{a}} \times \underline{\mathbf{b}}|}{2}$
- ▶ Vector product therefore gives the area of the parallelogram:  
 $A_{\text{parallelogram}} = |\underline{\mathbf{a}} \times \underline{\mathbf{b}}|$
- ▶ Hence “vector area”  
 $\underline{\mathbf{A}}_{\text{parallelogram}} = \underline{\mathbf{a}} \times \underline{\mathbf{b}}$  where the vector points perpendicular to the plane of the parallelogram.



## 2.3 Examples

### Example 1

Find the area of a parallelogram defined by coordinates (0,0,0), (1,3,4) and (2,1,3).

- ▶ Make vectors  $\underline{\mathbf{a}} = (\underline{\mathbf{i}} + 3\underline{\mathbf{j}} + 4\underline{\mathbf{k}})$  and  $\underline{\mathbf{b}} = (2\underline{\mathbf{i}} + \underline{\mathbf{j}} + 3\underline{\mathbf{k}})$

$$\underline{\mathbf{a}} \times \underline{\mathbf{b}} = \begin{vmatrix} \underline{\mathbf{i}} & \underline{\mathbf{j}} & \underline{\mathbf{k}} \\ 1 & 3 & 4 \\ 2 & 1 & 3 \end{vmatrix}. \quad (2)$$

- ▶  $\underline{\mathbf{a}} \times \underline{\mathbf{b}} = (3 \times 3 - 4 \times 1)\underline{\mathbf{i}} - (1 \times 3 - 4 \times 2)\underline{\mathbf{j}} + (1 \times 1 - 3 \times 2)\underline{\mathbf{k}}$   
 $= 5\underline{\mathbf{i}} + 5\underline{\mathbf{j}} - 5\underline{\mathbf{k}}$
- ▶ Thus the area is  $\sqrt{(5^2 + 5^2 + 5^2)} = 8.7$

This method certainly beats  $1/2 \times \text{base} \times \text{height}$  !

## Example 2

Example of scalars and cross product:

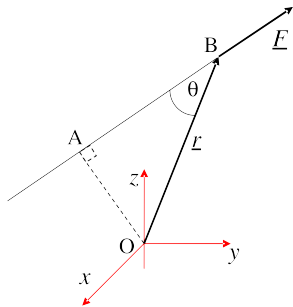
Show that if  $\underline{\mathbf{a}} = \underline{\mathbf{b}} + \lambda \underline{\mathbf{c}}$  for some scalar  $\lambda$ , then  $\underline{\mathbf{a}} \times \underline{\mathbf{c}} = \underline{\mathbf{b}} \times \underline{\mathbf{c}}$ .

- ▶ Solution:  $\underline{\mathbf{a}} = \underline{\mathbf{b}} + \lambda \underline{\mathbf{c}} \Rightarrow$   
 $\underline{\mathbf{a}} \times \underline{\mathbf{c}} = (\underline{\mathbf{b}} + \lambda \underline{\mathbf{c}}) \times \underline{\mathbf{c}} = \underline{\mathbf{b}} \times \underline{\mathbf{c}} + \lambda \underline{\mathbf{c}} \times \underline{\mathbf{c}}$
- ▶ but  $\underline{\mathbf{c}} \times \underline{\mathbf{c}} = \mathbf{0}$
- ▶ so  $\underline{\mathbf{a}} \times \underline{\mathbf{c}} = \underline{\mathbf{b}} \times \underline{\mathbf{c}}$  QED

## Examples of vector products in Physics

### ► a) Torque

A *torque* about O due to a force  $\underline{\mathbf{F}}$  acting at B :  $\underline{\mathbf{T}} = \underline{\mathbf{r}} \times \underline{\mathbf{F}}$ . Torque is a vector with direction perpendicular to both  $\underline{\mathbf{r}}$  and  $\underline{\mathbf{F}}$ , magnitude of  $|\underline{\mathbf{r}}||\underline{\mathbf{F}}| \sin \theta$ .



### ► b) Angular momentum

A body with momentum  $\underline{\mathbf{p}}$  at position  $\underline{\mathbf{r}}$  has angular momentum about O of  $\underline{\mathbf{L}} = \underline{\mathbf{r}} \times \underline{\mathbf{p}}$ . Angular momentum is a vector with direction perpendicular to both  $\underline{\mathbf{r}}$  and  $\underline{\mathbf{p}}$ , magnitude of  $|\underline{\mathbf{r}}||\underline{\mathbf{p}}| \sin \theta$ .

### ► c) Lorentz force

The force exerted by a magnetic field  $\underline{\mathbf{B}}$  on a charge  $q$  moving with velocity  $\underline{\mathbf{v}}$  is given by  $\underline{\mathbf{F}} = q\underline{\mathbf{v}} \times \underline{\mathbf{B}}$