

*LECTURE 11:*  
*THE INVERSE AND RANK OF A*  
*MATRIX AND SIMULTANEOUS*  
*EQUATIONS IN MATRIX FORM*

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# *Outline: 11. THE INVERSE AND RANK OF A MATRIX AND SIMULTANEOUS EQUATIONS IN MATRIX FORM*

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## 11.1 Prescription for finding the inverse of a matrix

For a square matrix  $A$ :  $AA^{-1} = A^{-1}A = I$

Prescription to find  $A^{-1}$ :

1. Start from a square matrix  $A$

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix} \quad (1)$$

2. Form the matrix of cofactors of  $A$ :

$$C = \begin{pmatrix} C_{11} & C_{12} & \cdots & C_{1n} \\ C_{21} & C_{22} & \cdots & C_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ C_{n1} & C_{n2} & \cdots & C_{nn} \end{pmatrix} \quad (2)$$

where cofactor  $C_{ij} = [\text{minor}] \times [\text{sign}] = M_{ij} \times (-1)^{(i+j)}$  as before.

3. Take the transpose  $C \Rightarrow C^T$  (the adjugate matrix)
4. Divide by the determinant of  $A$ .

Then the elements of  $A^{-1}$  are

$$(A^{-1})_{ik} = (C^T)_{ik} / |A| = C_{ki} / |A|$$

If  $|A| = 0$ , the matrix the matrix has no inverse (i.e. singular).

## 11.2 Proof for a general $3 \times 3$ matrix

- ▶ Start from  $A^{-1}A = I$
- ▶ Taking a general element of the LHS  
 $(A^{-1}A)_{ij} = \sum_k (A^{-1})_{ik} A_{kj}$
- ▶ Now we **assume the postulate**  $(A^{-1})_{ik} = (C^T)_{ik}/|A|$ 
  - ▶ Hence  $(A^{-1}A)_{ij} = \sum_k \frac{C_{ki}}{|A|} A_{kj} = I_{ij} = \delta_{ij} \rightarrow \text{Eqn (*)}$   
where  $\delta_{ij}$  is the Kronecker delta  
( $\delta_{ij} = 1$  for  $i = j$ ;  $= 0$  for  $i \neq j$ )
- ▶ **What we are going to do from here:** Consider a general  $3 \times 3$  matrix  $A$  and show that **Equ (\*)** is satisfied for both diagonal and off-diagonal elements in turn.

## The diagonal elements

- ▶ Take the general  $3 \times 3$  matrix:

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} \quad (3)$$

- ▶ Referring to [Equ \(\\*\)](#), consider  $\sum_k C_{ki} A_{kj} / |A|$  for diagonal elements  $i = j$ . Take as a specific example  $i = j = 1$

$$\frac{\sum_k C_{k1} A_{k1}}{|A|} = (C_{11} a_{11} + C_{21} a_{21} + C_{31} a_{31}) / |A|$$

- ▶ But  $\sum_k C_{k1} A_{k1}$  is the *determinant* from the first column

$$= a_{11} \times \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{21} \times \begin{vmatrix} a_{12} & a_{13} \\ a_{32} & a_{33} \end{vmatrix} + a_{31} \times \begin{vmatrix} a_{12} & a_{13} \\ a_{22} & a_{23} \end{vmatrix} = |A| \quad (4)$$

- ▶ i.e. when  $i = j = 1$ ,  $\frac{\sum_k C_{ki} A_{ki}}{|A|} = \frac{|A|}{|A|} = 1 = \delta_{ii}$  (cf. [Equ \(\\*\)](#))  
Also true had we taken  $i = j = 2$  or  $i = j = 3$ .

So the diagonal elements are consistent with the postulate.

## The off-diagonal elements

- ▶ Next consider  $\sum_k C_{ki} A_{kj} / |A|$  for  $i \neq j$  in Equ (\*):

- ▶ Take a specific example ( $i = 1, j = 2$ )

$$\sum_k C_{k1} A_{k2} = C_{11} a_{12} + C_{21} a_{22} + C_{31} a_{32}$$

$$= a_{12} \times \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{22} \times \begin{vmatrix} a_{12} & a_{13} \\ a_{32} & a_{33} \end{vmatrix} + a_{32} \times \begin{vmatrix} a_{12} & a_{13} \\ a_{22} & a_{23} \end{vmatrix} \quad (5)$$

- ▶ Next re-create the full determinant:

$$\begin{vmatrix} a_{12} & a_{12} & a_{13} \\ a_{22} & a_{22} & a_{23} \\ a_{32} & a_{32} & a_{33} \end{vmatrix} = 0 \quad [\text{since columns 1 and 2 have equal elements}]. \quad (6)$$

- ▶ So  $\sum_k C_{ki} A_{kj} / |A| = 0$  for  $i \neq j$  (cf. Equ (\*))  $\Rightarrow \delta_{ij} = 0$ .  
Also true had we taken any values  $i \neq j$ .

So the non-diagonal elements are also consistent with the postulate.

- ▶ We conclude that as a general result,  $A^{-1} = C^T / |A|$

## 11.3 Inverse of $2 \times 2$ matrix

- ▶ Start with matrix  $A$ :

$$A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \quad (7)$$

- ▶ The determinant is  $|A| = (a_{11}a_{22} - a_{12}a_{21})$
- ▶ The matrix of cofactors is:

$$C = \begin{pmatrix} a_{22} & -a_{21} \\ -a_{12} & a_{11} \end{pmatrix} \quad (8)$$

- ▶ The inverse of  $A$  is

$$A^{-1} = C^T / |A| = \frac{1}{(a_{11}a_{22} - a_{12}a_{21})} \begin{pmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{pmatrix} \quad (9)$$

- ▶ This is general for a  $2 \times 2$  matrix and is easy to remember.

### 11.3.1 Example

$$A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \quad (10)$$

$$A^{-1} = \frac{1}{(1 \times 4 - 2 \times 3)} \begin{pmatrix} 4 & -2 \\ -3 & 1 \end{pmatrix} \quad (11)$$

$$= -\frac{1}{2} \times \begin{pmatrix} 4 & -2 \\ -3 & 1 \end{pmatrix} = \begin{pmatrix} -2 & 1 \\ 3/2 & -1/2 \end{pmatrix} \quad (12)$$

Check:

$$A^{-1}A = \begin{pmatrix} -2 & 1 \\ 3/2 & -1/2 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \quad (13)$$

$$= \begin{pmatrix} -2 \times 1 + 1 \times 3 & -2 \times 2 + 1 \times 4 \\ 3/2 \times 1 - 1/2 \times 3 & 3/2 \times 2 - 4 \times 1/2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \text{ as required.} \quad (14)$$



## 11.4 Rank of a matrix

- ▶ Two equivalent definitions:
  - ▶ The *rank* of an  $m \times n$  matrix is defined as the number of *linear independent* rows or columns in the matrix (whichever is the smallest).
  - ▶ Alternatively the rank of an  $m \times n$  matrix is equal to the size of the largest *square* sub-matrix that is contained in the  $m$  rows and  $n$  columns of the matrix whose determinant is non-zero.
- ▶ Hence the rank of matrix  $A$  is always  $\leq$  to the *smaller* of  $m$  or  $n$ .
- ▶ For an  $n \times n$  square matrix,  $|A| = 0$  unless the rank =  $n$ .

### 11.4.1 Example

$$3 \times 3 \text{ matrix } A = \begin{pmatrix} 1 & 1 & 0 \\ 2 & 0 & 2 \\ 4 & 1 & 3 \end{pmatrix} \quad (15)$$

$$|A| = \begin{vmatrix} 1 & 1 & 0 \\ 2 & 0 & 2 \\ 4 & 1 & 3 \end{vmatrix} = 1 \times (-2) - 1 \times (6 - 8) + 0 = 0 \quad (16)$$

However a number of sub-matrices are non-zero:

$$\begin{vmatrix} 1 & 1 \\ 2 & 0 \end{vmatrix} = -2, \quad \begin{vmatrix} 1 & 1 \\ 4 & 1 \end{vmatrix} = -3, \quad \begin{vmatrix} 0 & 2 \\ 1 & 3 \end{vmatrix} = -2 \quad (17)$$

Hence the rank of this matrix is 2

## 11.5 Simultaneous equations in matrix form

- ▶ Use matrix methods to solve simultaneous linear equations:

$$\begin{array}{ccccccccc} a_{11}x_1 & + & a_{12}x_2 & + & \cdots & + & a_{1n}x_n & = & b_1 \\ a_{21}x_1 & + & a_{22}x_2 & + & \cdots & + & a_{2n}x_n & = & b_2 \\ \cdots & + & \cdots & + & \cdots & + & \cdots & = & \cdots \\ a_{m1}x_1 & + & a_{m2}x_2 & + & \cdots & + & a_{mn}x_n & = & b_m \end{array} \quad (18)$$

where  $a_{ij}$  and  $b_i$  have known values,  $x_i$  are unknown.

- ▶ If the  $b_i$  are all zero, then the system of equations is called *homogeneous*, otherwise its *inhomogeneous*.
- ▶ We can write the set of equations as a matrix equation:  
 $Ax = b$ , ( $A$  is called the *coefficient matrix*). i.e.

$$\begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \\ \cdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \cdots \\ b_m \end{pmatrix} \quad (19)$$

- ▶ We can define the *augmented matrix*

$$\left( \begin{array}{cccc|c} a_{11} & a_{12} & \cdots & a_{1n} & b_1 \\ a_{21} & a_{22} & \cdots & a_{1n} & b_2 \\ \cdots & \cdots & \cdots & \cdots & \cdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} & b_m \end{array} \right) \quad (20)$$

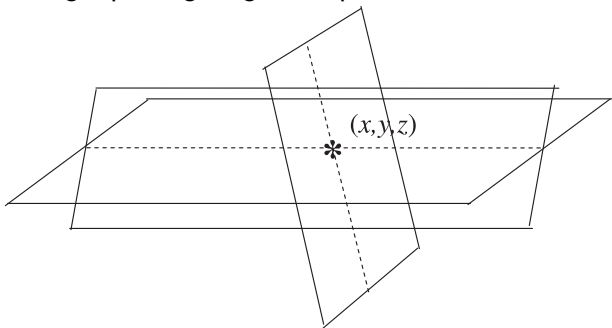
## 11.6 Unique solutions to simultaneous equations

- ▶ We have the case of  $n$  simultaneous equations in  $n$  unknowns: condition for the solution to be unique:
  - ▶ [Rank of coefficient matrix] = [Rank of augmented matrix] = [Number of unknowns]
  - ▶ OR alternatively for the coefficient matrix  $|A| \neq 0$  and  $\underline{b} \neq 0$ .
- ▶ Note that  $|A| \neq 0$  and  $\underline{b} = 0$  gives the trivial solution  $(x_1, x_2, \dots, x_n) = (0, 0, \dots, 0)$ .
- ▶ From here consider  $n = 3$

$$\begin{aligned}a_{11}x + a_{12}y + a_{13}z &= b_1 \\a_{21}x + a_{22}y + a_{23}z &= b_2 \\a_{31}x + a_{32}y + a_{33}z &= b_3\end{aligned}\tag{21}$$

## 11.6.1 Geometrical interpretation

- ▶ The geometrical representation is 3 planes intersecting at a single point giving a unique solution.



- ▶ i.e. the scalar triple product
$$(a_{11}, a_{12}, a_{13}) \cdot [(a_{21}, a_{22}, a_{23}) \times (a_{31}, a_{32}, a_{33})] \neq 0$$
- ▶ For the trivial solution  $|A| \neq 0$  and  $\underline{b} = 0$ , planes intersect at  $(0, 0, 0)$