

LECTURE 10:
DETERMINANTS

Prof. N. Harnew
University of Oxford
MT 2012

Outline: 10. DETERMINANTS

10.1 DETERMINANTS: What is a determinant?

10.2 Evaluating a general $N \times N$ determinant

10.3 Evaluating Det of a 3×3 matrix “rigorously”

10.4 Extend to 4×4

10.5 Properties of determinants

10.6 Evaluate a 4×4 determinant

10.7 The adjugate matrix

10.1 DETERMINANTS: What is a determinant?

- ▶ A determinant is a scalar, $\det(A) \equiv |A|$, which is associated with any *square* matrix A (must be square).
- ▶ Start by simply *quoting* the determinants up to $n = 3$:

- ▶ for a 1×1 matrix $\Rightarrow \det(A) = A$

- ▶ for a 2×2 matrix

$$\det(A) = \det \begin{pmatrix} a_1 & a_2 \\ b_1 & b_2 \end{pmatrix} \equiv \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} = a_1 b_2 - a_2 b_1 \quad (1)$$

- ▶ for a 3×3 matrix

$$\det(A) = \det \begin{pmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{pmatrix} \equiv \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} \quad (2)$$

$$= a_1 \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - a_2 \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + a_3 \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix} \quad (3)$$

$$= a_1 \times (b_2 c_3 - b_3 c_2) - a_2 \times (b_1 c_3 - b_3 c_1) + a_3 \times (b_1 c_2 - b_2 c_1)$$

10.2 Evaluating a general $N \times N$ determinant

- ▶ For an $N \times N$ matrix A , for each element A_{ij} we define a *minor* M_{ij}
- ▶ M_{ij} is the determinant of the $(N-1) \times (N-1)$ matrix obtained from A by deleting row i and column j .
- ▶ We also define *cofactor* $C_{ij} = (-1)^{(i+j)} M_{ij}$ (the “signed” minor of the same element).
- ▶ The determinant is then defined as the sum of the products of the elements of any row or column with their corresponding cofactors.

$$\text{i.e. } \det(A) = \sum_{j=1}^N A_{mj} C_{mj} = \sum_{i=1}^N A_{ik} C_{ik}$$

for ANY row m or column k .

10.3 Evaluating Det of a 3×3 matrix “rigorously”

- ▶ Take the 3×3 matrix

$$|A| = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} \quad (4)$$

- ▶ First knock out the first row and first column. Then the cofactor (1,1) is:

$$C_{11} = (-1)^{(1+1)} \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} \quad (5)$$

- ▶ Now get the next cofactor. Knock out the first row and second column:

$$C_{12} = (-1)^{(1+2)} \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} \quad (6)$$

- ▶ Then knock out the first row and third column:

$$C_{13} = (-1)^{(1+3)} \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix} \quad (7)$$

- ▶ This gives $\det(A) = a_1 C_{11} + a_2 C_{12} + a_3 C_{13}$

More on the Det of a 3×3

▶ From before: $\det(A) = a_1 C_{11} + a_2 C_{12} + a_3 C_{13}$

▶ Also, we can trivially show that the determinant is independent of the row or column chosen:

e.g. via the 2nd row: $\det(A) = b_1 C_{21} + b_2 C_{22} + b_3 C_{23}$

or via the 3rd column: $\det(A) = a_3 C_{13} + b_3 C_{23} + c_3 C_{33}$

▶ These equations are called *Laplace expansions* (or *Laplace developments*).

10.4 Extend to 4×4

$$|A| = \begin{vmatrix} a_1 & a_2 & a_3 & a_4 \\ b_1 & b_2 & b_3 & b_4 \\ c_1 & c_2 & c_3 & c_4 \\ d_1 & d_2 & d_3 & d_4 \end{vmatrix} \quad (8)$$

- Sum over 4 terms of cofactors: $|A| = \sum_{i=1}^4 a_i C_{1i}$

$$\begin{aligned} &= a_1 \times (-1)^{(1+1)} \times \begin{vmatrix} b_2 & b_3 & b_4 \\ c_2 & c_3 & c_4 \\ d_2 & d_3 & d_4 \end{vmatrix} + a_2 \times (-1)^{(1+2)} \times \begin{vmatrix} b_1 & b_3 & b_4 \\ c_1 & c_3 & c_4 \\ d_1 & d_3 & d_4 \end{vmatrix} + \\ &+ a_3 \times (-1)^{(1+3)} \times \begin{vmatrix} b_1 & b_2 & b_4 \\ c_1 & c_2 & c_4 \\ d_1 & d_2 & d_4 \end{vmatrix} + a_4 \times (-1)^{(1+4)} \times \begin{vmatrix} b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \\ d_1 & d_2 & d_3 \end{vmatrix} \end{aligned}$$

- Evaluating this will be very tedious if not done more efficiently. We strive to reduce elements of columns and/or rows to zero (see later).

10.5 Properties of determinants [1]

1. If we interchange 2 *adjacent* rows or 2 *adjacent* columns of A to give B , then $\det(B) = -\det(A)$

$$\text{e.g. } \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = - \begin{vmatrix} a_2 & a_1 & a_3 \\ b_2 & b_1 & b_3 \\ c_2 & c_1 & c_3 \end{vmatrix} \quad (9)$$

2. For a matrix A , the transpose satisfies

$$\det(A^T) = \det(A)$$

3. For a product of matrices then

$$\det(AB) = \det(BA) = \det(A) \times \det(B)$$

Properties of determinants [2]

4. If B results from multiplying one row or column of A by a scalar λ then $\det(B) = \lambda \times \det(A)$

$$\text{e.g. } \lambda \times \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = \begin{vmatrix} a_1 & \lambda a_2 & a_3 \\ b_1 & \lambda b_2 & b_3 \\ c_1 & \lambda c_2 & c_3 \end{vmatrix} = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ \lambda c_1 & \lambda c_2 & \lambda c_3 \end{vmatrix} \text{ etc.} \quad (10)$$

5. If I_n is an $n \times n$ unit matrix and λ a scalar, then

$$\det(I_n) = 1 \text{ and } \det(\lambda I_n) = \lambda^n$$

$$\text{Hence: } \det(\lambda A) = \det(\lambda I_n A) = \det(\lambda I_n) \det(A) = \lambda^n \det(A)$$

Properties of determinants [3]

6. For a matrix A , the inverse satisfies

$$\det(A^{-1}) = 1/\det(A)$$

Simple proof:

$$1 = \det(I) = \det(AA^{-1}) = \det(A) \det(A^{-1})$$
$$\rightarrow \det(A^{-1}) = 1/\det(A) \quad \text{QED}$$

7. For a matrix A where two or more rows (or columns) are equal or linearly dependent, then $\det(A) = 0$

$$\text{e.g. } \begin{vmatrix} a_1 & a_2 & a_3 \\ \lambda \times a_1 & \lambda \times a_2 & \lambda \times a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = 0 \quad (\text{where } \lambda \text{ is a scalar.})$$
$$(11)$$

Properties of determinants [4]

8. If B results from adding a multiple of one row to another row, or a multiple of one column to another column, then $\det(B) = \det(A)$ (determinant unchanged).

$$\text{e.g. } \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = \begin{vmatrix} a_1 & a_2 + \lambda \times a_1 & a_3 \\ b_1 & b_2 + \lambda \times b_1 & b_3 \\ c_1 & c_2 + \lambda \times c_1 & c_3 \end{vmatrix} \quad (\text{where } \lambda \text{ is a scalar.})$$

(12)

10.6 Evaluate a 4×4 determinant

$$\text{Evaluate } \begin{vmatrix} 1 & 3 & 0 & 4 \\ 3 & 7 & 2 & 9 \\ 1 & 0 & 2 & 4 \\ 0 & -1 & 4 & 3 \end{vmatrix} \quad (13)$$

Row 2 - ($3 \times$ row 1), put
answer in row 2

$$= \begin{vmatrix} 1 & 3 & 0 & 4 \\ 0 & -2 & 2 & -3 \\ 1 & 0 & 2 & 4 \\ 0 & -1 & 4 & 3 \end{vmatrix} \quad (14)$$

Row 3 - row 1, put
answer in row 3

$$= \begin{vmatrix} 1 & 3 & 0 & 4 \\ 0 & -2 & 2 & -3 \\ 0 & -3 & 2 & 0 \\ 0 & -1 & 4 & 3 \end{vmatrix} \quad (15)$$

From previous page

$$= \begin{vmatrix} 1 & 3 & 0 & 4 \\ 0 & -2 & 2 & -3 \\ 0 & -3 & 2 & 0 \\ 0 & -1 & 4 & 3 \end{vmatrix} \quad (16)$$

Laplace development of column 1

$$= (-1)^{(1+1)} \times 1 \times \begin{vmatrix} -2 & 2 & -3 \\ -3 & 2 & 0 \\ -1 & 4 & 3 \end{vmatrix} \quad (17)$$

Row 3 + row 1, put answer in row 3

$$= \begin{vmatrix} -2 & 2 & -3 \\ -3 & 2 & 0 \\ -3 & 6 & 0 \end{vmatrix} \quad (18)$$

Laplace development of column 3

$$= -3 \times (-1)^{(1+3)} \times \begin{vmatrix} -3 & 2 \\ -3 & 6 \end{vmatrix} \quad (19)$$

This is easily evaluated:

$$-3 \times ((-3 \times 6) - (2 \times -3)) = 36$$

10.7 The adjugate matrix

- ▶ The *adjugate matrix* is found by replacing each element of matrix A by its cofactor and then transposing the matrix.

$$\text{Adj}(A)_{ij} = C_{ij}^T = C_{ji}$$

- ▶ Note: the adjugate is sometimes called the *adjoint*, but that terminology is rather ambiguous. “Adjoint” of a matrix normally refers to the Hermitian conjugate (A^\dagger).