

CP2 ELECTROMAGNETISM

<https://users.physics.ox.ac.uk/~harnew/lectures/>

LECTURE 15: ELECTROMAGNETIC INDUCTION



Neville Harnew¹
University of Oxford
HT 2022

$$\begin{aligned}\nabla \cdot \mathbf{E} &= \frac{\rho}{\epsilon_0} \\ \nabla \cdot \mathbf{B} &= 0 \\ \nabla \times \mathbf{E} &= -\frac{\partial \mathbf{B}}{\partial t} \\ \frac{1}{\mu_0} \nabla \times \mathbf{B} &= \mathbf{J} + \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}\end{aligned}$$

OUTLINE : 15. ELECTROMAGNETIC INDUCTION

15.1 Summarizing where we are

15.1.1 Electrostatics

15.1.2 Magnetostatics

15.2 Electromagnetic induction - outline

15.3 Faraday and Lenz's Laws of Induction

15.3.1 Electromotive force (EMF)

15.3.2 Magnetic flux

15.4 Faraday's and Lenz's Laws

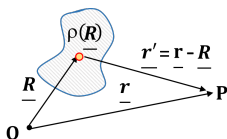
15.5 Faraday's Law in differential form

15.1.1 Summarizing where we are : electrostatics

1. Coulomb's Law :

$$\underline{\mathbf{E}}(\underline{\mathbf{r}}) = \frac{1}{4\pi\epsilon_0} \int_V \frac{\rho(\underline{\mathbf{R}})}{(\underline{\mathbf{r}} - \underline{\mathbf{R}})^3} (\underline{\mathbf{r}} - \underline{\mathbf{R}}) dV$$

- ▶ An electric charge generates an electric field. Electric field lines begin and end on charge or at ∞ .



2. Gauss Law :

$$\underbrace{\oint_S \underline{\mathbf{E}} \cdot \underline{\mathbf{d}\mathbf{a}} = Q_{encl.}/\epsilon_0}_{\text{integral form}} \rightarrow \underbrace{\nabla \cdot \underline{\mathbf{E}} = \rho/\epsilon_0}_{\text{differential form}}$$

3. The electric field is conservative :

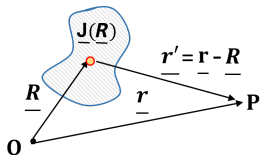
- ▶ A well-defined potential V such that $\underline{\mathbf{E}} = -\underline{\nabla} V$
 $\rightarrow \oint \underline{\mathbf{E}} \cdot \underline{\mathbf{d}\ell} = 0$ (work done is independent of path)
- ▶ Using the vector identity : $\underline{\nabla} \times \underline{\mathbf{E}} = -\underline{\nabla} \times \underline{\nabla} V = 0$
- ▶ Hence $\underline{\nabla} \times \underline{\mathbf{E}} = 0$

15.1.2 Summarizing where we are : magnetostatics

1. Biot-Savart Law :

$$\underline{\mathbf{B}}(\underline{\mathbf{r}}) = \frac{\mu_0}{4\pi} \int_V \frac{\underline{\mathbf{J}}(\underline{\mathbf{R}})}{(\underline{\mathbf{r}} - \underline{\mathbf{R}})^3} \times (\underline{\mathbf{r}} - \underline{\mathbf{R}}) dV$$

- ▶ There are no magnetic monopoles.
Magnetic field lines form closed loops.



2. Gauss Law of magnetostatics :

$$\underbrace{\oint_S \underline{\mathbf{B}} \cdot \underline{\mathbf{d}\mathbf{a}} = 0}_{\text{integral form}} \rightarrow \underbrace{\underline{\nabla} \cdot \underline{\mathbf{B}} = 0}_{\text{differential form}}$$

3. Ampere's Law :

- ▶ Magnetic fields are generated by electric currents.

$$\rightarrow \oint \underline{\mathbf{B}} \cdot \underline{\mathbf{d}\ell} = \mu_0 I_{encl.} \rightarrow \underline{\nabla} \times \underline{\mathbf{B}} = \mu_0 \underline{\mathbf{J}}$$

4. Continuity equation :

- ▶ $\int_S \underline{\mathbf{J}} \cdot \underline{\mathbf{d}\mathbf{a}} = -\frac{d}{dt} \int_V \rho(V) dV \rightarrow \underline{\nabla} \cdot \underline{\mathbf{J}} = -\frac{d}{dt}(\rho)$
(charge conserved)

Vector and scalar potential

Off syllabus, but worth a mention

Magnetic vector potential \mathbf{A} defined through: $\mathbf{B} = \nabla \times \mathbf{A}$

Such \mathbf{A} always exists because: $\nabla \cdot \mathbf{B} = \nabla \cdot (\nabla \times \mathbf{A}) = 0$

Inserting into Ampere's law: $\nabla \times \mathbf{B} = \nabla \times (\nabla \times \mathbf{A})$
 $= \nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} = \mu_0 \mathbf{J}$

There is a certain degree of freedom in which \mathbf{A} to choose – set: $\nabla \cdot \mathbf{A} = 0$

Poisson equations for magnetostatics:

(one for each \mathbf{J} & \mathbf{A} coordinate)

$$\nabla^2 \mathbf{A} = -\mu_0 \mathbf{J}$$

Magnetic scalar potential V_m :

$$\mathbf{B} = -\mu_0 \nabla V_m \longleftrightarrow V_m = -\frac{1}{\mu_0} \int_A^B \mathbf{B} \cdot d\mathbf{l}$$

Caution: V_m is *pathway-dependent and not single-valued* because $\nabla \times \mathbf{B} \neq 0$.

But V_m can be used with care in simply-connected, current-free regions.

Being a scalar, V_m is mathematically easier to use than the vector potential.

15.2 Electromagnetic induction - outline

Up to now we have considered stationary charges and steady currents. We now focus on what happens when either the E -field or B -field varies with time.

1. Introduction: Electromagnetic Induction
2. Faraday's and Lenz's Laws of Induction
3. Self-Inductance and Mutual Inductance
4. The Transformer
5. Energy of the Magnetic Field
6. Charged Particles in E- and B-Fields



Problem
Set 4

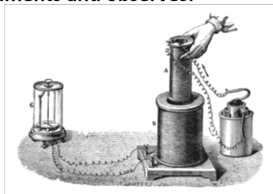


Problem
Set 5

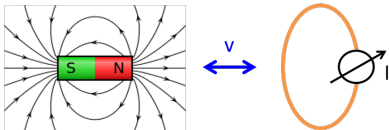
Origins of electromagnetic induction

1831: Michael Faraday carries out a series of experiments and observes:

Two coils are arranged in a way so that the magnetic flux density of coil A penetrates through coil B. He found that if the B-field in coil A is changing, this induces an electrical current in coil B.



Moving a bar magnet through a circuit element (wire loop) generates a current in the circuit. Moving instead the circuit w.r.t. the bar magnet, gives the same result.



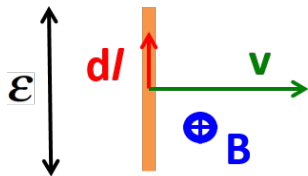
A change with time in the magnetic flux density through a circuit causes an “electromotive force” that moves charges along the circuit.

15.3 Faraday and Lenz's Laws of Induction

15.3.1 Electromotive force (EMF)

- ▶ Consider a wire moving with velocity \underline{v} through a B -field.
- ▶ Free charges in the wire experience a Lorentz force, perpendicular to \underline{v} & \underline{B} :

$$\underline{F} = q\underline{v} \times \underline{B}$$



- ▶ This moves charge to one side/end of the wire, which will create an electric potential drop along the wire :

$$\mathcal{E} = \int_{\ell} \frac{dW}{q} = \int_{\ell} \frac{\underline{F} \cdot d\underline{\ell}}{q} \quad (\text{by definition, } V = \text{work/unit charge})$$

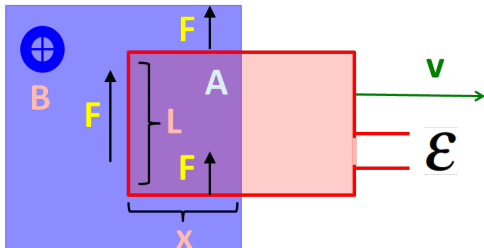
- ▶ Hence $\mathcal{E} = \int_{\ell} (\underline{v} \times \underline{B}) \cdot d\underline{\ell}$

\mathcal{E} is the *electromotive force* (or *electromotance*) (EMF)

- ▶ Note that \mathcal{E} is *not* a force but a line integral over a force (i.e. a potential) !

15.3.2 Magnetic flux

- ▶ Now consider a wire circuit loop being pulled with velocity \underline{v} out of a region containing a B -field.
- ▶ EMF on vertical side :



$$\begin{aligned}\mathcal{E} &= \int_{\ell} (\underline{v} \times \underline{B}) \cdot \underline{d\ell} \\ &= v B L\end{aligned}$$

- ▶ No contribution to EMF from horizontal sides
- ▶ Define *magnetic flux* $\Phi = \int_S \underline{B} \cdot \underline{da}$

- ▶ Rate of change of flux $\frac{d\Phi}{dt} = \frac{d}{dt} \int_S \underline{B} \cdot \underline{da} = \frac{d}{dt} \int_S B da$
(since \underline{B} is \parallel to \underline{da})

- ▶ $\frac{d\Phi}{dt} = \frac{d}{dt}(BA) = \frac{d}{dt}(BLx) = B \frac{dx}{dt} L = -v B L = -\mathcal{E}$
(negative since x decreases with positive v)

- ▶ In general, \mathcal{E} from magnetic flux $\frac{d\Phi}{dt} = \frac{d}{dt} \int_S \underline{B} \cdot \underline{da} = -\mathcal{E}$

15.4 Faraday's and Lenz's Laws

- ▶ Faraday's Law

The induced electromotive force (EMF) \mathcal{E} in any closed circuit is equal to (the negative of) the time rate of change of the magnetic flux Φ through the circuit.

$$\frac{d\Phi}{dt} = \frac{d}{dt} \int_S \underline{\mathbf{B}} \cdot \underline{\mathbf{d}\mathbf{a}} = -\mathcal{E}$$

- ▶ Lenz's Law

The induced electromotive force always gives rise to a current whose magnetic field opposes the original change in magnetic flux.

15.5 Faraday's Law in differential form

- ▶ Net potential around a *closed* circuit loop = 0

$$\mathcal{E} = \oint_{\ell} \underline{\mathbf{E}} \cdot \underline{\mathbf{d}\ell}, \quad \text{hence } V = -\mathcal{E} = -\oint_{\ell} \underline{\mathbf{E}} \cdot \underline{\mathbf{d}\ell}$$

- ▶ Faraday's Law in integral form

$$\mathcal{E} = \oint_{\ell} \underline{\mathbf{E}} \cdot \underline{\mathbf{d}\ell} = -\frac{d}{dt} \int_S \underline{\mathbf{B}} \cdot \underline{\mathbf{d}\mathbf{a}}$$

Apply Stokes' theorem to LHS :

$$\int_S (\nabla \times \underline{\mathbf{E}}) \cdot \underline{\mathbf{d}\mathbf{a}} = -\frac{d}{dt} \int_S \underline{\mathbf{B}} \cdot \underline{\mathbf{d}\mathbf{a}}$$

- ▶ Gives Faraday's Law in differential form

$$\nabla \times \underline{\mathbf{E}} = -\frac{\partial \underline{\mathbf{B}}}{\partial t}$$

- ▶ Any time-varying magnetic field (or change in magnetic flux) generates an electric field which results in an electric potential \mathcal{E} .

(In contrast $\nabla \times \underline{\mathbf{E}} = 0$ for electro/magneto-statics)