# CP2 ELECTROMAGNETISM

https://users.physics.ox.ac.uk/~harnew/lectures/

## LECTURE 15:

# ELECTROMAGNETIC INDUCTION



Neville Harnew<sup>1</sup>
University of Oxford
HT 2022

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\varepsilon_0}$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$\frac{1}{\mu_0} \nabla \times \mathbf{B} = \mathbf{J} + \varepsilon_0 \frac{\partial \mathbf{E}}{\partial t}$$



<sup>&</sup>lt;sup>1</sup>With thanks to Prof Laura Herz

#### OUTLINE: 15. ELECTROMAGNETIC INDUCTION

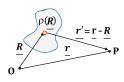
- 15.1 Summarizing where we are
  - 15.1.1 Electrostatics
  - 15.1.2 Magnetostatics
- 15.2 Electromagnetic induction outline
- 15.3 Faraday and Lenz's Laws of Induction
  - 15.3.1 Electromotive force (EMF)
  - 15.3.2 Magnetic flux
- 15.4 Faraday's and Lenz's Laws
- 15.5 Faraday's Law in differential form

## 15.1.1 Summarizing where we are : electrostatics

#### 1. Coulomb's Law:

$$\underline{\mathbf{E}}(\underline{\mathbf{r}}) = rac{1}{4\,\pi\,\epsilon_0} \int_{\mathcal{V}} rac{
ho(\underline{\mathbf{R}})}{(\underline{\mathbf{r}}-\underline{\mathbf{R}})^3} (\underline{\mathbf{r}}-\underline{\mathbf{R}})\,\mathrm{d}\mathcal{V}$$

An electric charge generates an electric field. Electric field lines begin and end on charge or at  $\infty$ .



#### 2. Gauss Law:

$$\underbrace{\oint_{\mathcal{S}} \underline{\mathbf{E}} \cdot \underline{\mathbf{da}} = Q_{\textit{encl.}}/\epsilon_0}_{\textit{integral form}} \quad \rightarrow \quad \underbrace{\nabla \cdot \underline{\mathbf{E}} = \rho/\epsilon_0}_{\textit{differential form}}$$

- 3. The electric field is conservative:
  - A well-defined potential V such that  $\underline{\mathbf{E}} = -\underline{\nabla} V$   $\rightarrow \oint \underline{\mathbf{E}} \cdot \underline{\mathbf{d}} \ell = 0$  (work done is independent of path) Using the vector identity :  $\underline{\nabla} \times \underline{\mathbf{E}} = -\underline{\nabla} \times \underline{\nabla} V = 0$ Hence  $\underline{\nabla} \times \underline{\mathbf{E}} = 0$

## 15.1.2 Summarizing where we are: magnetostatics

#### 1. Biot-Savart Law:

$$\underline{\mathbf{B}}(\underline{\mathbf{r}}) = rac{\mu_0}{4\pi} \int_{\mathcal{V}} rac{\underline{\mathbf{J}}(\underline{\mathbf{R}})}{(\mathbf{r}-\mathbf{R})^3} imes (\underline{\mathbf{r}} - \underline{\mathbf{R}}) \, d\mathcal{V}$$

- There are no magnetic monopoles.
   Magnetic field lines form closed loops.
- $\begin{array}{c}
  \underline{J(R)} \\
  \underline{r'} = \underline{r} \underline{R} \\
  \underline{r} \\
  \underline{r}
  \end{array}$

#### 2. Gauss Law of magnetostatics:

$$\underbrace{\oint_{\mathcal{S}} \underline{\mathbf{B}} \cdot \underline{\mathbf{da}} = \mathbf{0}}_{\text{integral form}} \quad \rightarrow \quad \underbrace{\nabla \cdot \underline{\mathbf{B}} = \mathbf{0}}_{\text{differential form}}$$

- 3. Ampere's Law:
  - Magnetic fields are generated by electric currents.

$$\rightarrow \quad \oint \mathbf{B} \cdot \mathbf{d}\ell = \mu_0 \, I_{\text{encl.}} \quad \rightarrow \quad \underline{\nabla} \times \mathbf{B} = \mu_0 \, \mathbf{J}$$

4. Continuity equation:

$$\int_{\mathcal{S}} \underline{\mathbf{J}} \cdot \underline{\mathbf{da}} = -\frac{d}{dt} \int_{\mathcal{V}} \rho(\mathcal{V}) \, d\mathcal{V} \quad \rightarrow \quad \underline{\nabla} \cdot \underline{\mathbf{J}} = -\frac{d}{dt}(\rho)$$
 (charge conserved)

## Vector and scalar potential

#### Off syllabus, but worth a mention

Magnetic vector potential A defined through:  $\mathbf{B} = \nabla \times \mathbf{A}$ 

Such **A** always exists because:  $abla \cdot \mathbf{B} = 
abla \cdot (
abla imes \mathbf{A}) = 0$ 

Inserting into Ampere's law:  $abla imes \mathbf{B} = 
abla imes (
abla imes \mathbf{A})$ 

$$= \nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} = \mu_0 \mathbf{J}$$

There is a certain degree of freedom in which **A** to choose – set:

$$\nabla \cdot \mathbf{A} = 0$$

Poisson equations for magnetostatics:

(one for each J & A coordinate)

$$\nabla^2 \mathbf{A} = -\mu_0 \mathbf{J}$$

Magnetic scalar potential  $V_m$ :

$$\mathbf{B} = -\mu_0 \nabla V_m \iff V_m = -\frac{1}{\mu_0} \int_A^B \mathbf{B} \cdot d\mathbf{l}$$

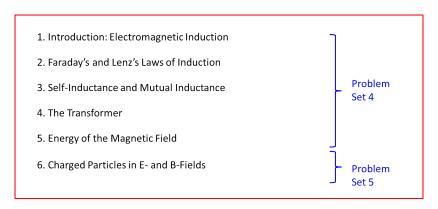
**Caution:**  $V_m$  is pathway-dependent and not single-valued because  $\nabla imes \mathbf{B} \neq 0$ .

But  $V_m$  can be used with care in simply-connected, current-free regions.

Being a scalar,  $V_m$  is mathematically easier to use than the vector potential.

## 15.2 Electromagnetic induction - outline

Up to now we have considered stationary charges and steady currents. We now focus on what happens when either the *E*-field or *B*-field varies with time.

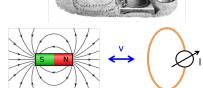


## Origins of electromagnetic induction

#### 1831: Michael Faraday carries out a series of experiments and observes:

Two coils are arranged in a way so that the magnetic flux density of coil A penetrates through coil B. He found that if the B-field in coil A is changing, this induces an electrical current in coil B.

Moving a bar magnet through a circuit element (wire loop) generates a current in the circuit. Moving instead the circuit w.r.t. the bar magnet, gives the same result.



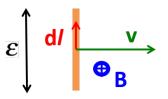


A change with time in the magnetic flux density through a circuit causes an "electromotive force" that moves charges along the circuit.

## 15.3 Faraday and Lenz's Laws of Induction

#### 15.3.1 Electromotive force (EMF)

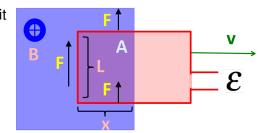
Consider a wire moving with velocity velocity



Note that ℰ is not a force but a line integral over a force (i.e. a potential)!

### 15.3.2 Magnetic flux

 Now consider a wire circuit loop being pulled with velocity v out of a region containing a B-field.



▶ In general,  $\mathcal{E}$  from magnetic flux

$$\frac{d\Phi}{dt} = \frac{d}{dt} \int_{S} \mathbf{\underline{B}} \cdot \mathbf{\underline{da}} = -\mathcal{E}$$

## 15.4 Faraday's and Lenz's Laws

## ▶ Faraday's Law

The induced electromotance (EMF)  ${\cal E}$  in any closed circuit is equal to (the negative of) the time rate of change of the magnetic flux  $\Phi$  through the circuit.

$$\frac{d\Phi}{dt} = \frac{d}{dt} \int_{\mathcal{S}} \mathbf{\underline{B}} \cdot \mathbf{\underline{da}} = -\mathcal{E}$$

#### Lenz's Law

The induced electromotance always gives rise to a current whose magnetic field opposes the original change in magnetic flux.

## 15.5 Faraday's Law in differential form

▶ Any time-varying magnetic field (or change in magnetic flux) generates an electric field which results in an electric potential *E*.

(In contrast  $\nabla \times \mathbf{E} = \mathbf{0}$  for electro/magnito-statics)