Lecture 19. Spinors

1. Def: a 'vector+flag' that can be mapped onto a pair of complex numbers: $\boldsymbol{s} = \begin{pmatrix} a \\ b \end{pmatrix}$

2. Extracting a null 4-vector from a spinor:

where $I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$, $\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$, $\sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$, $\sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$.

3. Rotating the coordinate system: spinor $\boldsymbol{s} \to U \boldsymbol{s}$

$$U_x = e^{i(\theta/2)\sigma_x} = \cos(\theta/2)I + i\sin(\theta/2)\sigma_x = \begin{pmatrix} \cos(\theta/2) & i\sin(\theta/2) \\ i\sin(\theta/2) & \cos(\theta/2) \end{pmatrix},$$

$$U_y = e^{i(\theta/2)\sigma_y} = \cos(\theta/2)I + i\sin(\theta/2)\sigma_y = \begin{pmatrix} \cos(\theta/2) & \sin(\theta/2) \\ -\sin(\theta/2) & \cos(\theta/2) \end{pmatrix},$$

$$U_z = e^{i(\theta/2)\sigma_z} = \cos(\theta/2)I + i\sin(\theta/2)\sigma_z = \begin{pmatrix} e^{i\theta/2} & 0 \\ 0 & e^{-i\theta/2} \end{pmatrix}.$$

 $\mathsf{X}^{\mu} = \left\langle s \right| \sigma^{\mu} \left| s \right\rangle$

4. Any 2×2 matrix Λ with unit determinant Lorentz-transforms a spinor. Such matrices can be written

$$\Lambda = \exp\left(i\boldsymbol{\sigma}\cdot\boldsymbol{\theta}/2 - \boldsymbol{\sigma}\cdot\boldsymbol{\rho}/2\right)$$

where ρ is rapidity and θ is rotation angle. If Λ is unitary the transformation is a rotation in space; if Λ is Hermitian it is a boost.

5. Main idea: $\begin{cases} 1st rank spinor & \leftrightarrow & null 4-vector \\ one type of 2nd rank spinor & \leftrightarrow & any 4-vector (\Rightarrow transformation rule) \end{cases}$

- 1. Spinor basics
- i. A "spinor" is essentially a mathematical tool.
- ii. A rank 1 spinor is very much like a 4-vector; (a rank 2 spinor is like a tensor).
- iii. Spinors are used in quantum as well as classical physics; we shall only do classical physics.
- iv. Everything you can do with vectors and tensors you can also do with spinors!
- v. But don't worry, we will focus on describing just two basic physical quantities: energy-momentum and angular-momentum.

Two ways of thinking about a spinor.

1. It is a two-component vector having complex coefficients:

$$\boldsymbol{s} = \begin{pmatrix} a \\ b \end{pmatrix}$$
 $(a, b \in \text{complex numbers})$

2. It is a null 4-vector, with real (not complex) components, with a 'flag' attached.

If we write the spinor as

$$s = se^{i\alpha/2} \left(\begin{array}{c} \cos(\theta/2)e^{-i\phi/2} \\ \sin(\theta/2)e^{i\phi/2} \end{array}
ight)$$

then the associated 4-vector (sometimes called 'flagpole') is

$$\begin{pmatrix} r\\r\sin\theta\cos\phi\\r\sin\theta\sin\phi\\r\cos\theta \end{pmatrix}$$

where $r = s^2$. The spatial (3-vector) part can also be called a Bloch vector.

Lecture 20. Chirality, Weyl equations, Dirac spinor

1. contraspinor $\mathbf{s}'_R = \Lambda \mathbf{s}_R, \qquad \mathbf{X}^{\mu} = \langle s_R | \sigma^{\mu} | s_R \rangle$ cospinor $\mathbf{s}'_L = (\Lambda^{\dagger})^{-1} \mathbf{s}'_L, \qquad \mathbf{X}_{\mu} = \langle s_L | \sigma^{\mu} | s_L \rangle$

contraspinor is called "right handed" or "+ve chirality" cospinor is called "left handed" or "-ve chirality" we don't call contravariant 4-vectors "right handed") but this terminology invites confusion (e.g.

2. Weyl equations and parity violation

$$\mathsf{P}_{\lambda} \sigma^{\lambda} \boldsymbol{w}_{R} = 0 \qquad \Rightarrow (E/c - \mathbf{p} \cdot \boldsymbol{\sigma}) \boldsymbol{w}_{R} = 0,$$

$$\mathsf{P}_{\lambda} \sigma^{\lambda} \boldsymbol{w}_{L} = 0 \qquad \Rightarrow (E/c + \mathbf{p} \cdot \boldsymbol{\sigma}) \boldsymbol{w}_{L} = 0.$$

 \rightarrow eigenvalue equations, helicity is positive/negative for contraspinors/cospinors.

3. Treat massive particles using a pair of spinors, ϕ_R , χ_L . Form U = A - B, W = (A + B)mcS: pair of orthogonal non-null 4-vectors. Hence

 $\mathsf{U}^{\mu} = \Psi^{\dagger} \gamma^{0} \gamma^{\mu} \Psi, \qquad \mathsf{W}^{\mu} = mcS \Psi^{\dagger} \Sigma^{\mu} \Psi,$ where $\gamma^{0} = \begin{pmatrix} 0 & I \\ I & 0 \end{pmatrix}, \quad \gamma^{i} = \begin{pmatrix} 0 & -\sigma^{i} \\ \sigma^{i} & 0 \end{pmatrix}$ "Dirac matrices"

4. Lorentz transform of Dirac spinor: $\Psi \to \begin{pmatrix} \Lambda(v) & 0 \\ 0 & \Lambda(-v) \end{pmatrix} \Psi$ leads to "particle Dirac equation"

$$\begin{pmatrix} -m & E + \boldsymbol{\sigma} \cdot \mathbf{p} \\ E - \boldsymbol{\sigma} \cdot \mathbf{p} & -m \end{pmatrix} \begin{pmatrix} \phi_R(\mathbf{p}) \\ \chi_L(\mathbf{p}) \end{pmatrix} = 0.$$

Lecture 21. Variations on the wave equation

1. Wave equation: $\Box^2 \phi = 0$ or $-\frac{1}{c^2} \frac{\partial^2 \phi}{\partial t^2} + \nabla^2 \phi = 0.$ Plane wave solutions

$$\phi(t,x,y,z) = \phi_0 e^{i(\mathbf{k}\cdot\mathbf{r}-\omega t)} \qquad \Rightarrow \omega^2 - k^2 c^2 = 0. \qquad (\text{c.f. } E^2 - p^2 c^2 = 0.)$$

2. Klein Gordan equation: $(\Box^2 - \mu^2 c^2)\phi = 0.$

Plane wave solutions: $\omega^2 - k^2 c^2 = \mu^2 c^4$ Associated 4-current $\mathbf{J} = i \left(\phi \Box \phi^* - \phi^* \Box \phi \right), \qquad \Box \cdot \mathbf{J} = 0$

3. Dirac equation in 1D (i.e. 1 spatial dimension plus time): zero mass:

$$\left(\frac{\partial}{\partial t} + c\frac{\partial}{\partial x}\right)\phi_1 = 0, \qquad \left(\frac{\partial}{\partial t} - c\frac{\partial}{\partial x}\right)\phi_2 = 0.$$

non-zero mass:

$$\begin{array}{lll} i\left(\frac{\partial}{\partial t} - c\frac{\partial}{\partial x}\right)\phi_1 &= \mu c^2\phi_2 \\ i\left(\frac{\partial}{\partial t} + c\frac{\partial}{\partial x}\right)\phi_2 &= \mu c^2\phi_1 \end{array} \right\} \qquad \Rightarrow \quad \left(\hat{\omega} + \sigma_z \hat{k}_x c\right)\psi = \mu c^2\sigma_x\psi$$

4. **Dirac equation in 3D** (i.e. 3 spatial dimensions plus time): zero mass:

$$\begin{aligned} &(\hat{\omega} - \boldsymbol{\sigma} \cdot \hat{\mathbf{k}}c)\phi_1 &= 0, \\ &(\hat{\omega} + \boldsymbol{\sigma} \cdot \hat{\mathbf{k}}c)\phi_2 &= 0. \end{aligned}$$

non-zero mass:

$$\begin{pmatrix} \hat{\omega} - \boldsymbol{\sigma} \cdot \hat{\mathbf{k}}c \end{pmatrix} \phi_R &= \mu c^2 \chi_L, \\ (\hat{\omega} + \boldsymbol{\sigma} \cdot \hat{\mathbf{k}}c) \chi_L &= \mu c^2 \phi_R \end{cases}$$
 or $i\gamma^{\lambda} \partial_{\lambda} \Psi = \mu c \Psi$

Dirac current $J^{\mu} = \psi^{\dagger} \gamma^{0} \gamma^{\mu} \psi = (\psi^{\dagger} \psi, c \psi^{\dagger} \alpha \psi)$ and 4-spin $W^{\mu} = \psi^{\dagger} \gamma^{0} \gamma^{\mu} \gamma^{5} \psi$